

III. Matrix Product States

In this chapter, we will consider one-dimensional spin chains, i.e. $\mathcal{H} = (\mathbb{C}^d)^{\otimes N}$,

$$\bullet \quad \bullet \quad \bullet \quad \bullet \quad \dots \quad \bullet \quad \bullet \quad \bullet \quad \bullet$$

$\dots \mathbb{C}^d \mathbb{C}^d \dots$

with states

$$|\psi\rangle = \sum_{i_1, \dots, i_N=0}^{d-1} c_{i_1 \dots i_N} |i_1, \dots, i_N\rangle$$

1. Construction

Consider $|\psi\rangle = \sum c_{i_1 \dots i_N} |i_1, \dots, i_N\rangle$.

We can think of $c_{i_1 \dots i_N}$ as a tensor with N indices; each index can take d values.

Graphical notation:

$$c_{i_1 \dots i_N} =$$

$i_1 \quad i_2 \quad \dots \quad i_N$
 $| \quad | \quad | \quad \dots \quad | \quad |$

c

Box = tensor

Since $|4\rangle$ and $c_{i_1 \dots i_N}$ are the same object (once we fix a basis), can also write

$$\boxed{|4\rangle}.$$

We can also consider

$$c_{i_1 i_2 \dots i_N} = c_{i_1}(i_2 \dots i_N) \text{ as a matrix}$$

with row-index i_1 and column-index $(i_2 \dots i_N)$ (i.e., a multi-index).

Now perform an SVD of $c_{i_1}(i_2 \dots i_N)$:

$$c_{i_1}(i_2 \dots i_N) = \sum_{\alpha_1, \alpha'_1} U_{i_1, \alpha_1} \Lambda_{\alpha_1, \alpha'_1} V_{\alpha'_1}(i_2, \dots, i_N)$$

$$(\text{or } C = U \Lambda V),$$

can replace by $\delta_{\alpha_1, \alpha'_1}$ & $V_{\alpha_1}(\dots)$

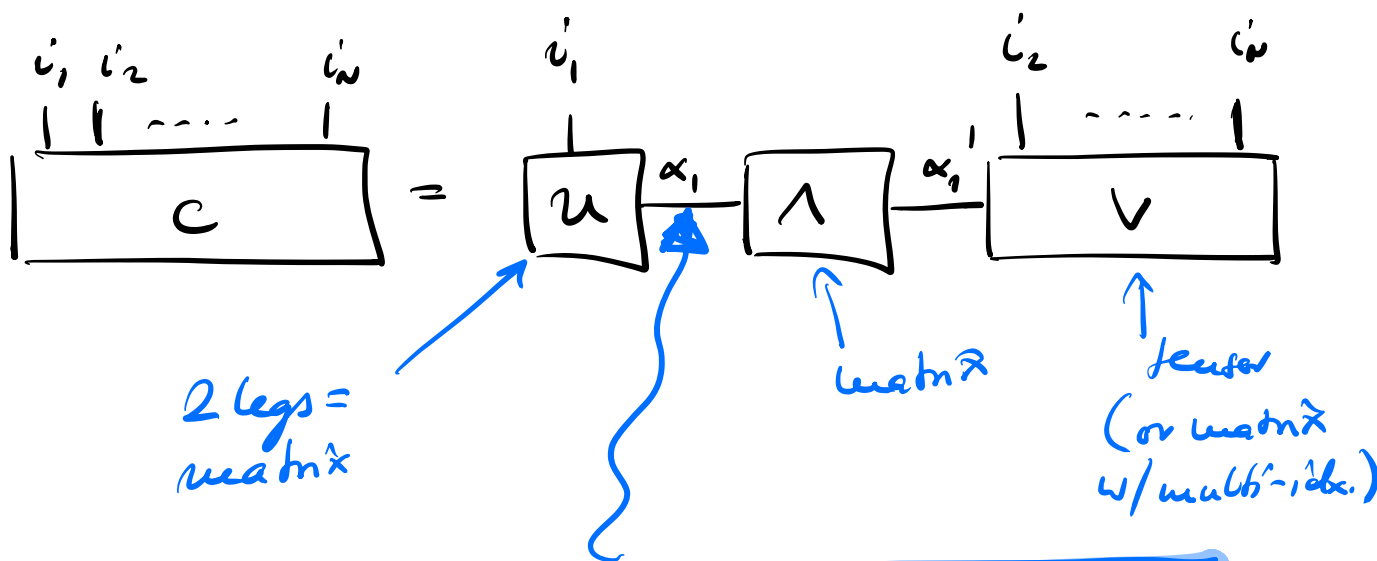
with Λ a diagonal matrix, $\Lambda_{\alpha_1, \alpha'_1} = \delta_{\alpha_1, \alpha'_1} \cdot \overset{0}{11} \lambda_{\alpha_1}$

and U, V^T isometries

$$\sum_{i_1} \overline{U_{i_1, \beta_1}} U_{i_1, \alpha_1} = \delta_{\alpha_1, \beta_1} \quad (\text{i.e. } U^T U = \mathbb{1})$$

$$\sum_{i_2 \dots i_n} \overline{V_{\beta_1, (i_2, \dots, i_n)}} V_{\alpha_1, (i_2, \dots, i_n)} = \delta_{\alpha_1, \beta_1} \quad (\text{i.e. } V V^T = \mathbb{1})$$

Graphically:



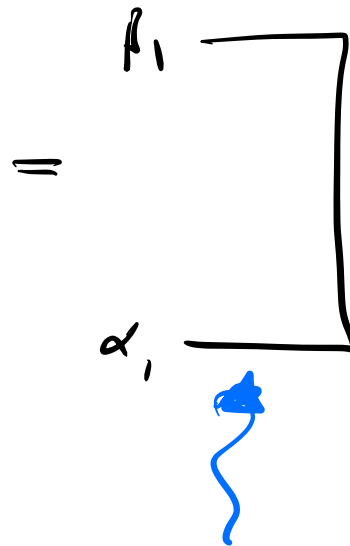
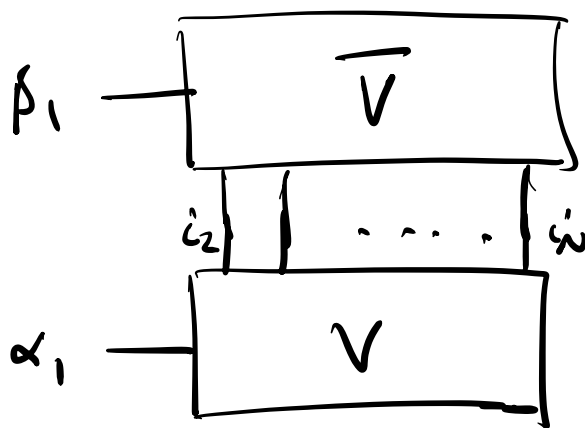
connecting legs denotes contraction: The legs are identified and summed over

E.g.: $i \text{---} \boxed{A} \text{---} \boxed{B} \text{---} j = \sum_k A_{ik} B_{kj} = (A \cdot B)_{ij}$

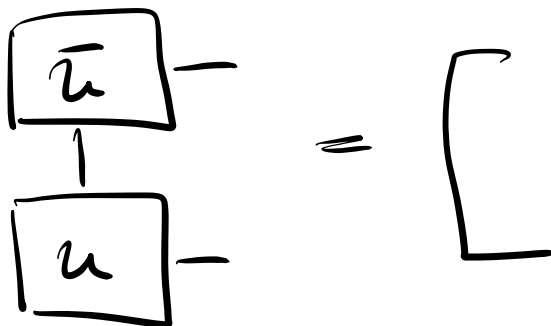
matrix
product!

The isometry conditions read
graphically:

$$\sum_{i_2 \dots i_N} \overline{V}_{\beta_1, (i_2, \dots, i_N)} V_{\alpha_1, (i_2, \dots, i_N)} = \delta_{\alpha_1, \beta_1}.$$



and



single line =
identity matrix

(consistent:

$$\begin{aligned} -[A] - [B] &= A \cdot B \\ &= A \cdot 1 \cdot B \\ &= 1 \cdot A \cdot B = \dots \end{aligned}$$

Express state $|\psi\rangle$ with U, λ, V : Chapter III, pg 5

$$|\psi\rangle = \sum_{\substack{i_1, i_2, \dots, i_N \\ \alpha_1}} U_{i_1 \alpha_1} \lambda_{\alpha_1 \alpha_1} V_{\alpha_1, (i_2, \dots, i_N)} |i_1, i_2, \dots, i_N\rangle$$

$$\textcircled{*} = \sum_{\alpha_1} \lambda_{\alpha_1 \alpha_1} \underbrace{\left(\sum_{i_1} U_{i_1 \alpha_1} |i_1\rangle \right)}_{=: |\ell_{\alpha_1}\rangle} \underbrace{\left(\sum_{i_2, \dots, i_N} V_{\alpha_1, (i_2, \dots, i_N)} |i_2, \dots, i_N\rangle \right)}_{=: |\alpha_1\rangle}$$

$$\langle \ell_{\beta} | \ell_{\alpha} \rangle = \sum_{ij, \alpha, \beta} U_{i\alpha} \overline{U_{j\beta}} \underbrace{\langle j | i \rangle}_{= \delta_{ij}}$$

$$= \sum U_{i\alpha} \overline{U_{i\beta}} = \delta_{\alpha\beta}$$

$\Rightarrow |\ell_{\alpha}\rangle$ (and $|\alpha\rangle$) ONS!

$\Rightarrow \textcircled{*}$ is the Schmidt decomposition of $|\psi\rangle$

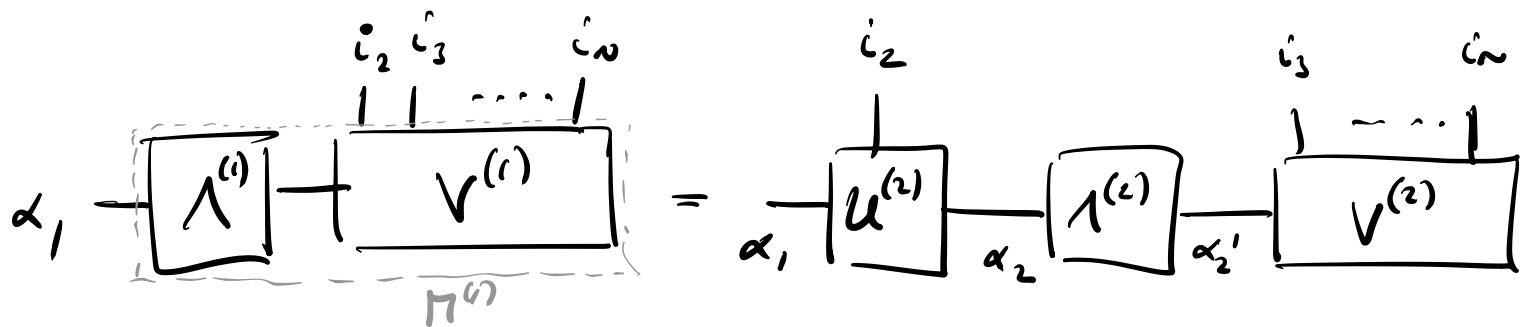
in the partition $\underbrace{1}_A | \underbrace{23 \dots N}_B$, with

$\lambda_{\alpha_1 \alpha_1}$ the Schmidt coefficients!

Now call $U = U^{(1)}$, $\Lambda = \Lambda^{(1)}$, $V = V^{(1)}$ Chapter III, pg 6

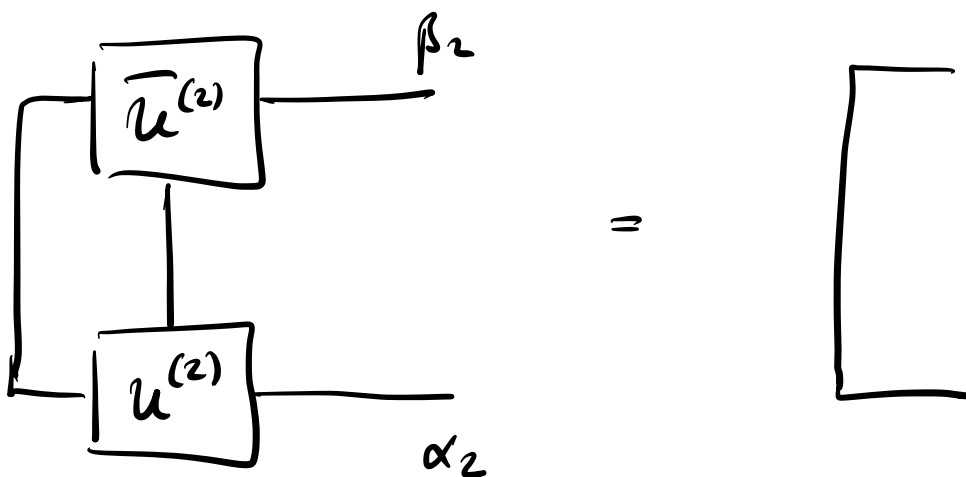
Consider $\Pi_{\alpha_1, i_2, (i_3 \dots i_n)}^{(1)} := \sum_{\alpha_1'} \Lambda_{\alpha_1, \alpha_1'} V_{\alpha_1', (i_2 \dots i_n)}^{(1)}$
new row/col. indices

Perform SVD of $\Pi^{(1)} \equiv \Lambda^{(1)} V^{(1)}$:

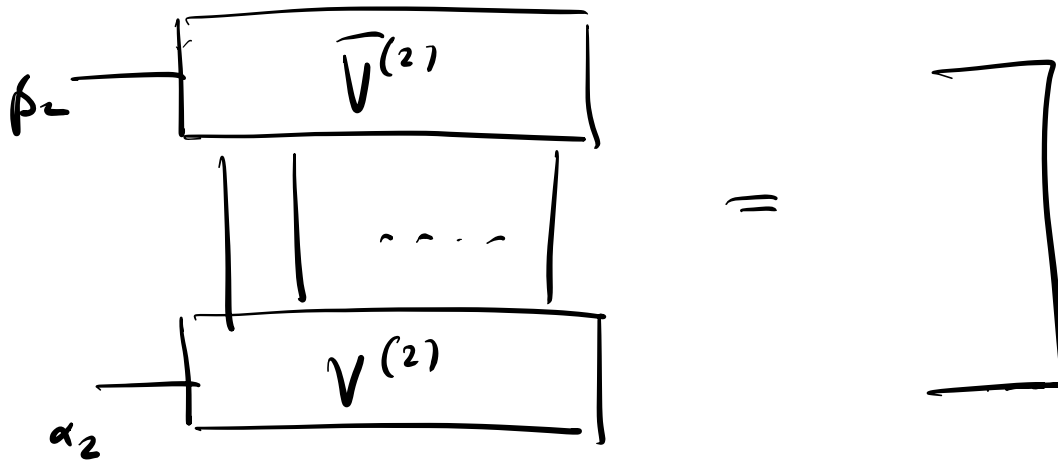


$\Lambda^{(2)}$ is diagonal ≥ 0

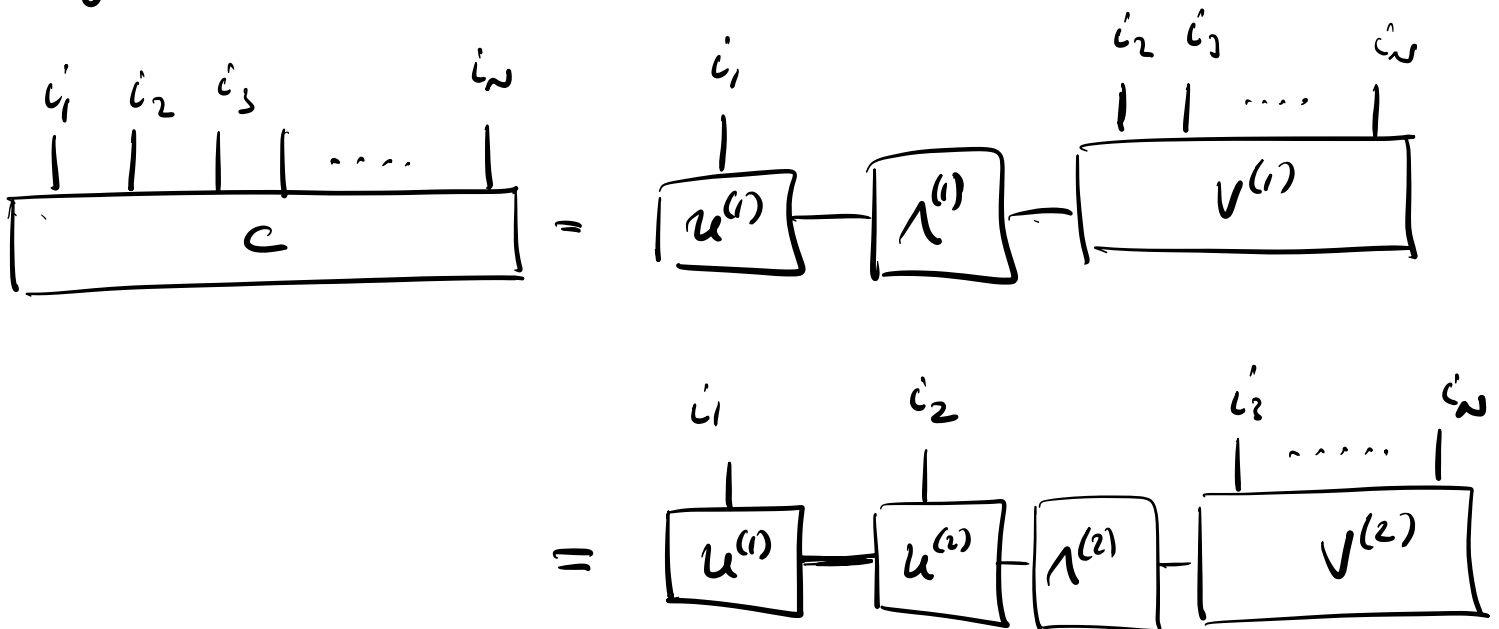
$U^{(2)}, V^{(2)}$ isometries:



$$\left(\text{or: } \sum_{\alpha_1, i_2} U_{(\alpha_1, i_2) \alpha_2}^{(2)} \bar{U}_{(\alpha_1, i_2) \beta_2}^{(2)} = \delta_{\alpha_2 \beta_2} \right)$$

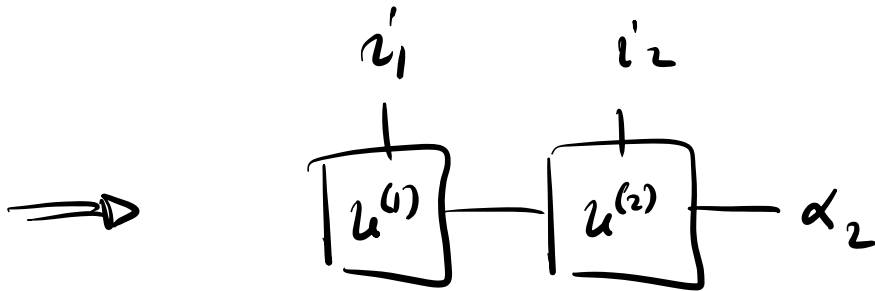
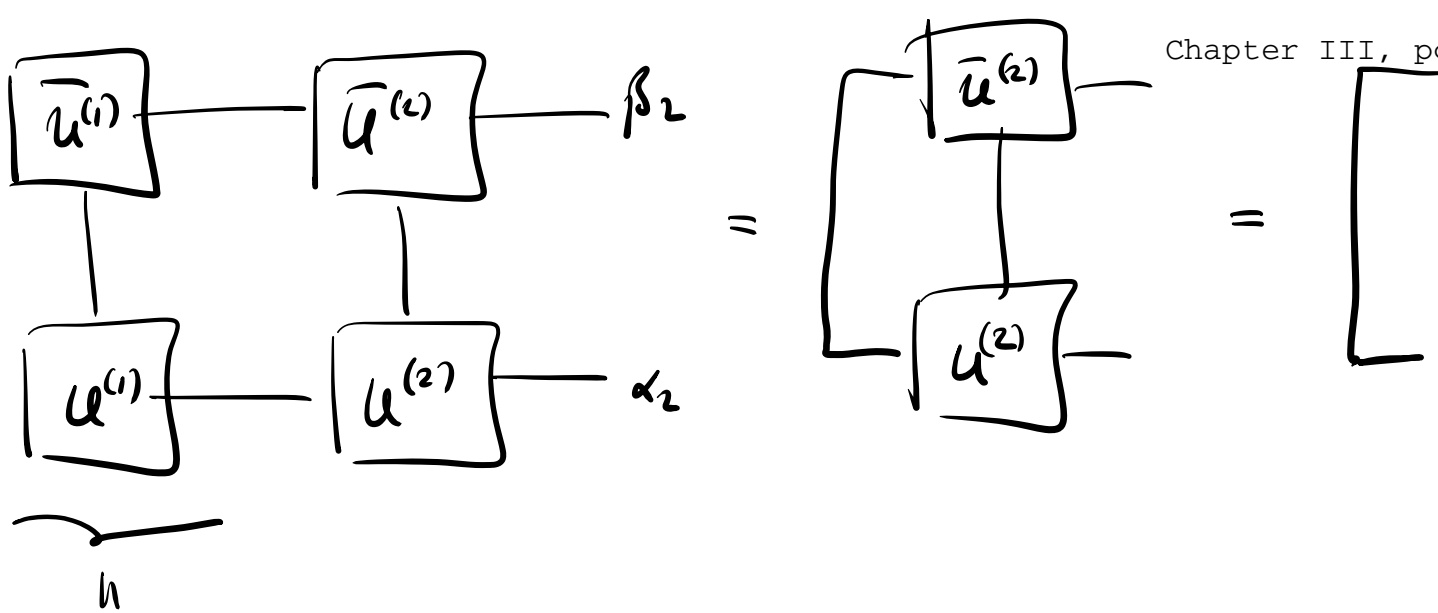


Together:



What is the form of the decomposition
in the cut $12|3 \dots N$?

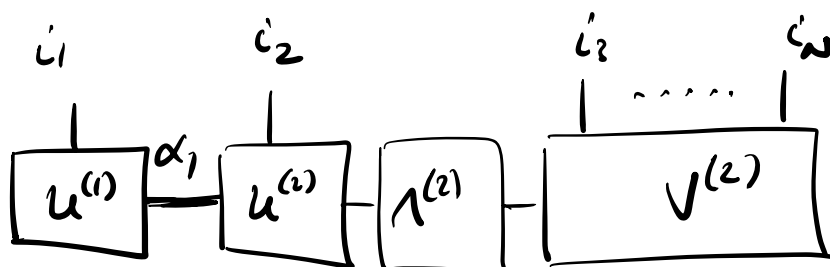
$V^{(2)}$ boundary $\Rightarrow$ right hand $\alpha_2 - \boxed{V}$ is OAB.



is also an isometry (as a map from $\alpha_2 \rightarrow (i_1, i_2)$)

$\Rightarrow$ this is again a Schmidt decomposition,
now in the cut $12/3 \dots N$.

Moreover, if we consider



$$= \begin{array}{c} i_1 \\ | \\ \boxed{u^{(1)}} \end{array} \xrightarrow{\alpha_1} \boxed{\Lambda^{(1)}} \xrightarrow{\quad} \begin{array}{c} i_2 \quad i_3 \quad \dots \quad i_N \\ | \quad | \quad \dots \quad | \\ \boxed{V^{(1)}} \end{array}$$

across the cut $1/2 \dots N$, then this still
gives a Schmidt-like decomposition

$$|\psi\rangle = \sum |\ell_{\alpha}^{(1)}\rangle |\tilde{r}_{\alpha}^{(1)}\rangle$$

$$\text{with } \langle \ell_{\alpha}^{(1)} | \ell_{\beta}^{(1)} \rangle = \delta_{\alpha\beta}$$

$$\text{and } \langle \tilde{r}_{\alpha}^{(1)} | \tilde{r}_{\beta}^{(1)} \rangle = \Lambda_{\alpha\alpha} \delta_{\alpha\beta}$$

Orthogonal, and the Schmidt
coefficients sorted in $|\tilde{r}_{\alpha}\rangle$

We can now iterate this scheme and get:

$$\begin{array}{c} i_1 \quad i_2 \quad \dots \quad i_N \\ \boxed{C} \end{array} = \begin{array}{c} i_1 \\ \boxed{u^{(1)}} \end{array} - \begin{array}{c} i_2 \\ \boxed{u^{(2)}} \end{array} - \dots - \begin{array}{c} i_{N-1} \\ \boxed{u^{(N-1)}} \end{array} - \underbrace{\begin{array}{c} \boxed{\wedge^{(N-1)}} \\ \boxed{v^{(N-1)}} \end{array}}_{i_N}$$

with

$$=: - \boxed{u^{(N)}}$$

$$\begin{array}{c} \boxed{\bar{u}^{(1)}} \\ \boxed{u^{(1)}} \end{array} = \left[\quad \right], \quad \begin{array}{c} \boxed{\bar{u}^{(k)}} \\ \boxed{u^{(k)}} \end{array} = \left[\quad \right] \quad (k=2, \dots, N-1)$$

and thus also

$$\begin{array}{c} \boxed{\bar{u}^{(1)}} - \boxed{\bar{u}^{(2)}} - \dots - \boxed{\bar{u}^{(N)}} \\ \boxed{u^{(1)}} - \boxed{u^{(2)}} - \dots - \boxed{u^{(N)}} \end{array} = \left[\quad \right]$$

$$= \left[\quad \right]$$

$$= \left[\quad \right]$$

— i.e., this representation gives a quasi-Schmidt decomposition in every cut $1 \dots k | (k+1) \dots N$, $k=1, \dots, N-1$:

$$\sum |e_{\alpha}^{(k)}\rangle |\tilde{r}_{\alpha}^{(k)}\rangle,$$

$$\langle e_{\beta}^{(k)} | e_{\alpha}^{(k)} \rangle = \delta_{\alpha\beta}$$

$$\langle \tilde{r}_{\beta}^{(k)} | \tilde{r}_{\alpha}^{(k)} \rangle = \lambda_{\alpha}^{(k)} \delta_{\alpha\beta}$$

 Schmidt coeffs for cut k .

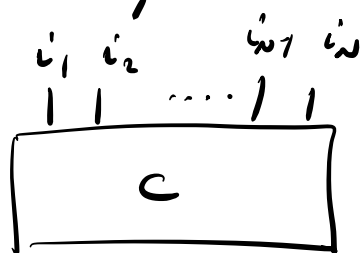
Alternatively, we can consider

$$\boxed{u^{(1)}}_{\alpha_1}^{i_1} \text{ as a set of row vectors } (u_{i_1}^{(1)})_{\alpha_1},$$

and $\boxed{u^{(k)}}_{\alpha_k}^{i_k} \text{ as matrices } (u_{i_k}^{(k)})_{\alpha_k, \beta_k},$

and $\boxed{u^{(N)}}_{\alpha_{N+1}}^{i_N} \text{ as a set of col. vectors } (u_{i_N}^{(N)})_{\alpha_{N+1}}.$

Then,



$$= \begin{array}{c} i_1 \\ \boxed{u^{(1)}} \end{array} - \begin{array}{c} i_2 \\ \boxed{u^{(2)}} \end{array} - \dots - \begin{array}{c} i_{N-1} \\ \boxed{u^{(N-1)}} \end{array} - \begin{array}{c} i_N \\ \boxed{u^{(N)}} \end{array}$$

$$= \underbrace{u_{i_1}^{(1)} \cdot u_{i_2}^{(2)} \cdot \dots \cdot u_{i_{N-1}}^{(N-1)} \cdot u_{i_N}^{(N)}}_{\text{vector} \cdot \text{matrix} \cdot \text{matrix} \cdot \dots \cdot \text{vector!}}$$

vector · matrix · matrix · ... · vector!

$$\Rightarrow |\psi\rangle = \sum u_{i_1}^{(1)} \cdot u_{i_2}^{(2)} \cdot \dots \cdot u_{i_{N-1}}^{(N-1)} \cdot u_{i_N}^{(N)} |i_1, \dots, i_N\rangle$$

"Matrix Product State" (MPS)

In general, we have:

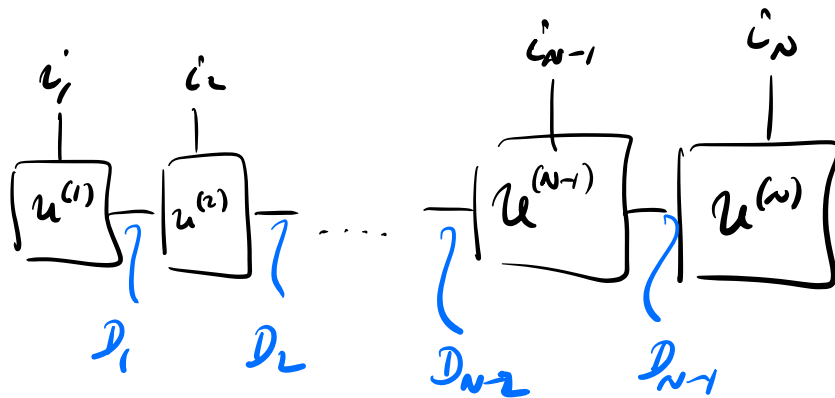
$$u_{i_1}^{(1)} : 1 \times D_1 - \text{vector}$$

$$u_{i_2}^{(2)} : D_1 \times D_2 - \text{matrix}$$

$$u_{i_k}^{(k)} : D_{k-1} \times D_k - \text{matrix}$$

⋮

$u_{i_N}^{(N)} : D_{N-1} \times 1$ - vector



We call D_i the "bond dimension".

Observation: We have re-phrased $c_{i_1} \dots c_{i_N}$ as a vector-matrix product!

Did this reduce the # of parameters?

No, this cannot be - this decomposition is exact & cannot reduce # of params.

In fact: At each cut, the bond dimension will generically be $\min(\dim(\text{left}), \dim(\text{right}))$,

e.g. with (d^k, d^{N-k}) , since D_k is the summation range of the Schmidt decomposition!

$\Rightarrow$ the bond dimension will be exponentially big

then we decompose an arbitrary state

$$|\psi\rangle = \sum c_{i_1 \dots i_n} |i_1 \dots i_n\rangle !$$

2. Truncation of the bond dimension & approximability by MPS

Can we reduce the # of parameters for states with small entanglement?

Have seen: for any path

$$\underbrace{0 \ 0 \ 0 \ 0 \ 0}_A \quad | \quad \underbrace{0 \ 0 \ 0 \ 0 \ 0}_B \quad |\psi_{AB}\rangle$$

We can cut the Schmidt decomposition

$$|\psi_{AB}\rangle = \sum_{i=1}^r s_i |e_i\rangle \otimes |r_i\rangle$$

to a smaller # of terms,

$$|\psi(x)\rangle = \sum_{i=1}^x s_i |e_i\rangle \otimes |r_i\rangle,$$

at an error $\epsilon(x)$ which scales moderately.

Step I Assume $\epsilon(x)=0$ (i.e.: S_0 -Renyi-entropy is bounded by $S_0 \leq \log x$):

Then, Schmidt decomposition at each cut k , chapter III, pg 16

$$|\psi\rangle = \sum_{i=1}^{D_k} s_i |l_i\rangle |r_i\rangle$$

has only χ non-zero terms, $D_k \leq \chi \forall k$!

$\Rightarrow$ In each step of the previous construction, the dimensions D_k of the matrices are $D_k \leq \chi$ (or, alternatively: The rank of the SVD is $\leq \chi$.)

$\Rightarrow$ For 1D states $|\psi\rangle$ with an area law for the O- Rényi entropy, $S_0(\rho_A) \leq \log \chi$,

the exact MPS decomposition of $|\psi\rangle$ has bond dimension $\leq \chi$, i.e.,

$$|\psi\rangle = \sum_{i_1 \dots i_N} U_{i_1}^{(1)} U_{i_2}^{(2)} \dots U_{i_N}^{(N)} |i_1 \dots i_N\rangle,$$

with $U_{i_k}^{(k)}$, $2 \leq k \leq N-1$ $X \times X$ -matrices.

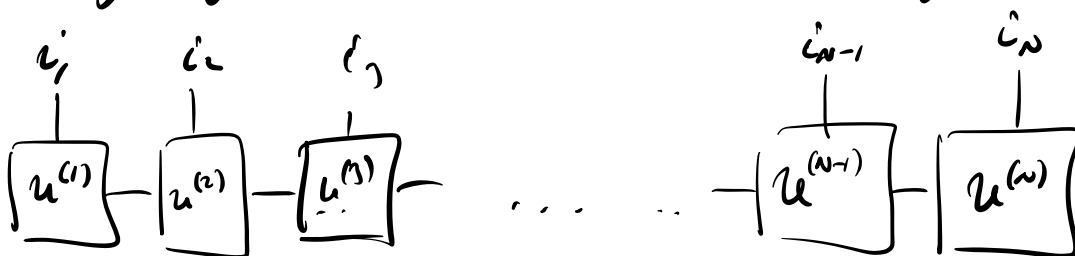
(Note: If a D_k is smaller than X , we can always pad it with zeros to obtain $X \times X$ matrices everywhere - if we want.

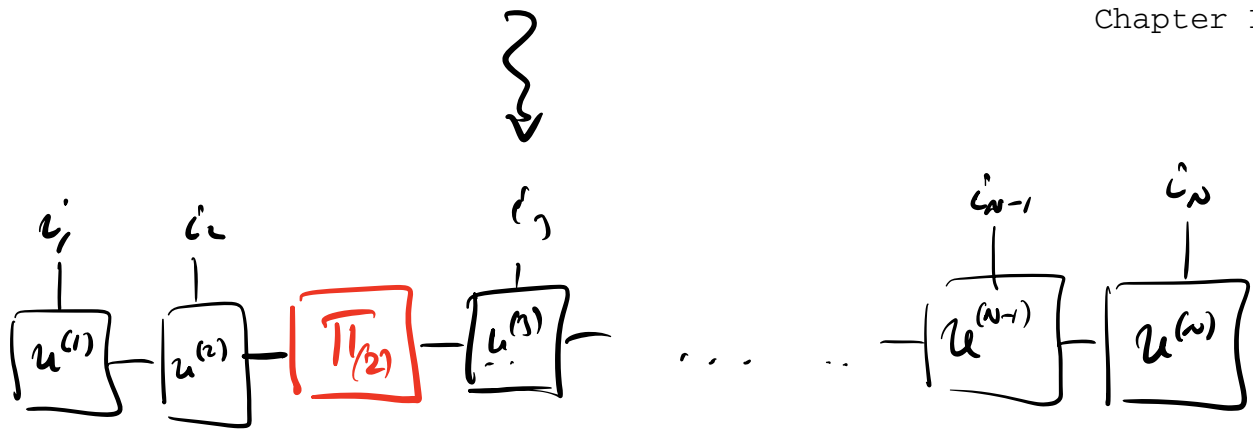
More generally, "bond dimension X " should generally be read as "bond dimension at most X ".)

Step II: What happens if the truncation is approximate, with error ϵ differs from prev. ϵ by factor 2.

$$\epsilon(X) = \| |\psi\rangle - |\psi(X)\rangle \|^2$$

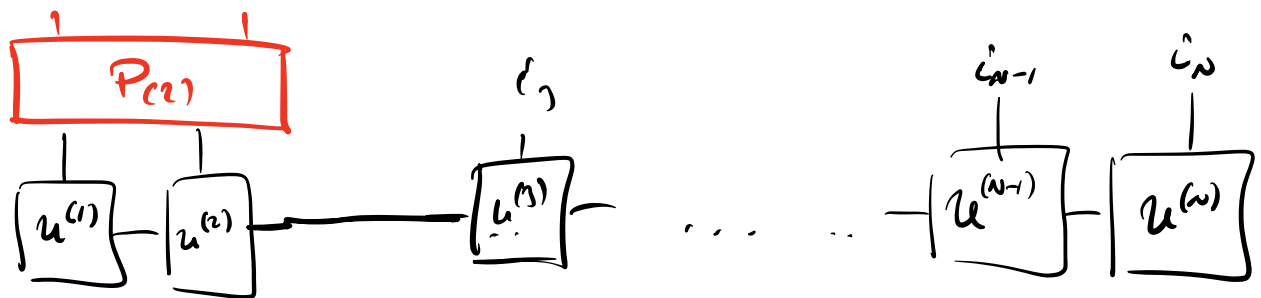
We can think of cutting the Schmidt rank at any given cut as changing





where $\Pi_{(2)}$ is the projector onto the χ target
Schmidt vectors!

... which again equals



with same projector $P_{(2)}$ (since $U^{(1)} - U^{(2)}$ is an isometry).

Then, define the truncated MPS as

$$|\hat{\phi}(\chi)\rangle = U^{(1)} \Pi_{(1)} U^{(2)} \Pi_{(2)} \dots \Pi_{(n-1)} U^{(n)}$$

$$= P_{(1)} \cdot P_{(2)} \cdot \dots \cdot P_{(n-1)} |\psi\rangle$$

We know that $\|P_{(s)} |\psi\rangle - |\psi\rangle\| \leq \sqrt{\epsilon(x)}$,

$$\text{or } P_{(s)} |\psi\rangle = |\psi\rangle + |\delta_s\rangle, \quad \|\delta_s\| \leq \sqrt{\epsilon},$$

and thus

$$\begin{aligned} \| \underbrace{P_{(N-2)} P_{(N-1)}}_{= |\psi\rangle + |\delta_{N-1}\rangle} |\psi\rangle - |\psi\rangle \| &\leq \underbrace{\|P_{(N-2)} |\psi\rangle - |\psi\rangle\|}_{\leq \sqrt{\epsilon}} + \underbrace{\|\delta_{N-1}\|}_{\leq \sqrt{\epsilon}}, \\ &= \|\psi\rangle + \|\delta_{N-1}\| \end{aligned}$$

and doing this telescopically:

$$\|P_{(0)} \cdots P_{(N-1)} |\psi\rangle - |\psi\rangle\| \leq \sqrt{\epsilon} \cdot N.$$

In fact, with a bit more care, we can find that the errors are independent, and thus

$$\epsilon_{\text{tot}} := \| |\psi\rangle - |\phi(x)\rangle \|^2 \leq N \cdot \epsilon$$

State where we have used the truncated Schmidt dec.
at all cuts.

We can now combine this with the fact that

$$\epsilon(\chi) \sim \left(\frac{eS_x}{\chi} \right)^\gamma :$$

strict area law, $S_x \leq \text{const.}$:

$$\epsilon(\chi) \sim \frac{1}{\chi^\gamma}, \text{ and thus}$$

$$\epsilon_{\text{tot}}(\chi) \sim \frac{N}{\chi^\gamma},$$

$$\text{or } \chi \sim \text{poly} \left(N, \frac{1}{\epsilon_{\text{tot}}} \right),$$

i.e. the χ ($\leftrightarrow$ # of parameters) required to describe a ground state to global error ϵ_{tot} scales polynomially with system size & accuracy.

For gapless systems with

$$S \leq c \log L \leq c \log N:$$

$$\varepsilon(x) \sim \left(\frac{e^{c \log N}}{x} \right)^{\gamma}$$

$$\sim \text{poly}(x, N),$$

and thus

$$\varepsilon_{\text{tot}}(x) \sim \text{poly}(x, N),$$

and $x \sim \text{poly}\left(\frac{1}{\varepsilon}, N\right)$

$\Rightarrow$ same type of (efficient) scaling
even for critical systems!

(Compare this to exponential scaling
of parameters $\sim N$ for exact state!)

Definition (from now on):

A Matrix Product State (MPS)

of bond dimension D is a state of the form

$$|\psi\rangle = \sum_{i_1, \dots, i_N} A^{i_1, (1)} A^{i_2, (2)} \dots A^{i_N, (N)} |i_1, \dots, i_N\rangle,$$

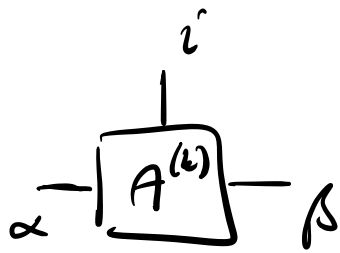
$$= \begin{array}{c} | \\ \boxed{A^{(1)}} \end{array} - \begin{array}{c} | \\ \boxed{A^{(2)}} \end{array} - \dots - \begin{array}{c} | \\ \boxed{A^{(N-1)}} \end{array} - \begin{array}{c} | \\ \boxed{A^{(N)}} \end{array}$$

with $A^{i_k, (k)}$, $k=2, \dots, N-1$ $D \times D$ -matrices,
and $A^{i_1, (1)}$ $1 \times D$, $A^{i_N, (N)}$ $D \times 1$ (i.e. vectors)

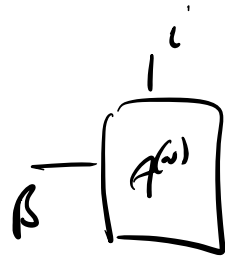
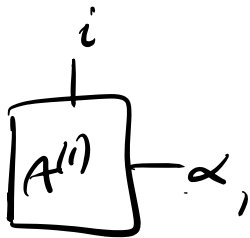
More generally, $A^{i_k, (k)}$ can be a $D_{k-1} \times D_k$ -matrix

$$D_0 = D_N = 1.$$

Terminology:



are 3-index (3-leg) tensors.



are 2-index tensors.

We call i the physical index (or degree of freedom, DoF), and

α, β the virtual or auxiliary indices/DoFs.

Since $\boxed{c_{i_1 \dots i_N}}$ is expressed as a network

of elementary tensors, such states are also called Tensor Network States.

A priori, the matrices $A^{i_{\alpha}, (k)}$ are unrestricted.

However, they can be brought into canonical forms.

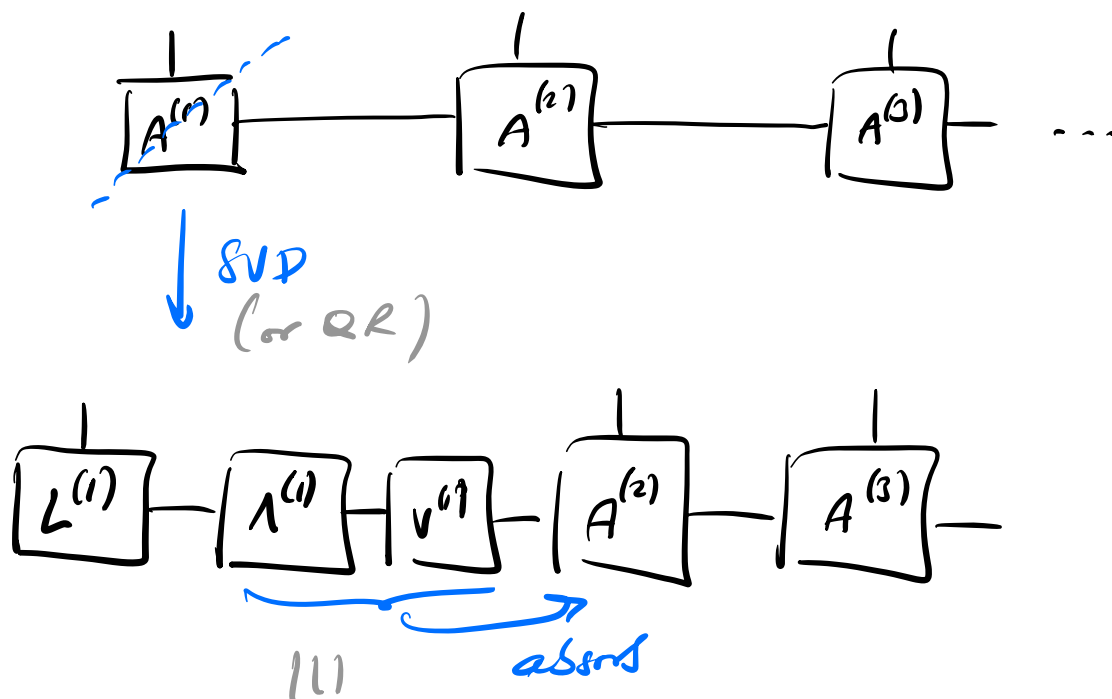
Left-canonical form:

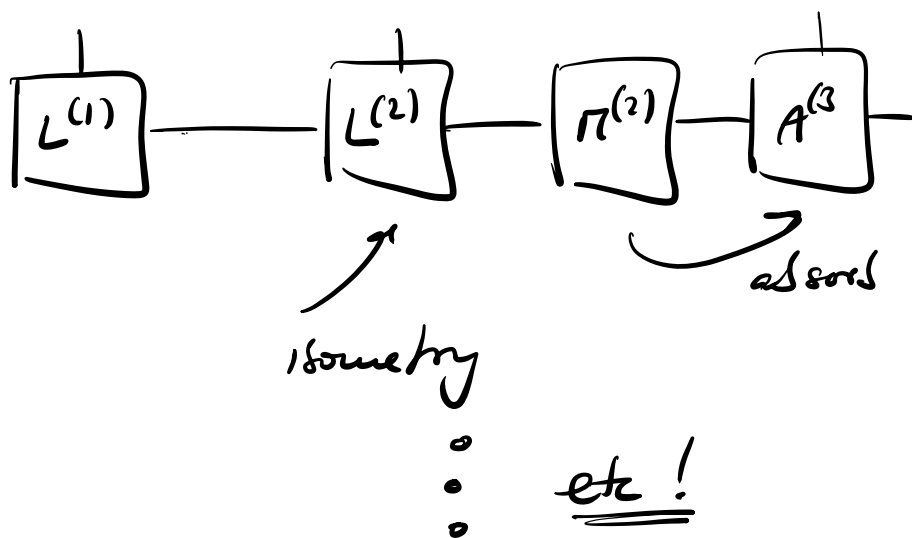
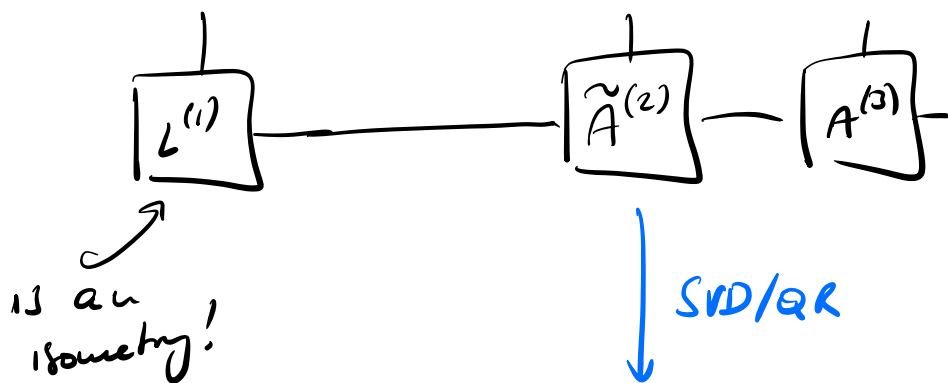
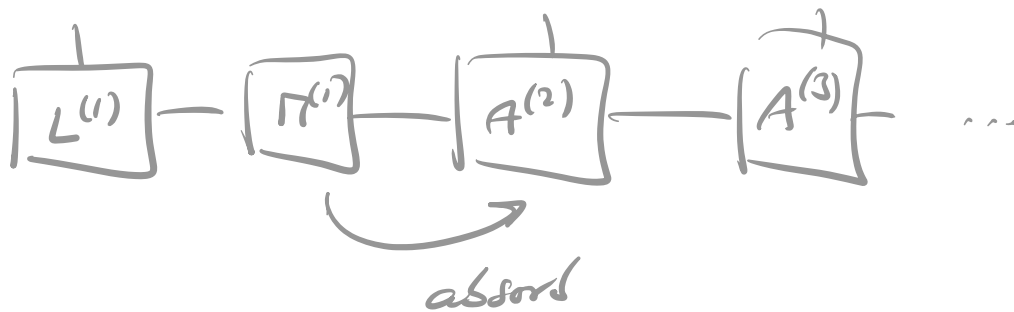
An MPS is said to be in left-canonical form,

$$|\psi\rangle = \boxed{L^{(1)}} - \boxed{L^{(2)}} - \dots - \boxed{L^{(N-1)}} - \boxed{L^{(N)}}$$

$$if \quad \begin{array}{c} \boxed{L^{(1)}} \\ | \\ \boxed{L^{(1)}} \end{array} = \left[\begin{array}{c} \boxed{L^{(k)}} \\ | \\ \boxed{L^{(k)}} \end{array} \right] = \left[\right] \quad (k < N).$$

Every MPS can be brought into left-canonical form by a sequence of local transformations (Exercise problem 3a):





⋮ etc!

Important: Size of matrices for SVD is $D \times dD$,
i.e. indep. of system size, & comp. cost $\sim D^3$
 $\Rightarrow$ MPS can be brought into can. form efficiently.

Analogously, we can define the

Right-canonical form (CF):

An MPS is said to be in right-canonical form,

$$|\psi\rangle = \overline{R^{(1)}} - \overline{R^{(2)}} - \dots - \overline{R^{(N-1)}} - \overline{R^{(N)}}$$

$$\text{if } \begin{array}{c} \overline{R^{(k)}} \\ | \\ \overline{R^{(k)}} \end{array} = \left[\begin{array}{c} \overline{R^{(k)}} \\ | \\ \overline{R^{(k)}} \end{array} \right], \quad \begin{array}{c} \overline{R^{(N)}} \\ | \\ \overline{R^{(N)}} \end{array} = \left[\begin{array}{c} \overline{R^{(N)}} \\ | \\ \overline{R^{(N)}} \end{array} \right]$$

$(1 \leq k \leq N)$

... and it can be brought into right-CF in an analogous way.

Finally, we can define a

Mixed canonical form:

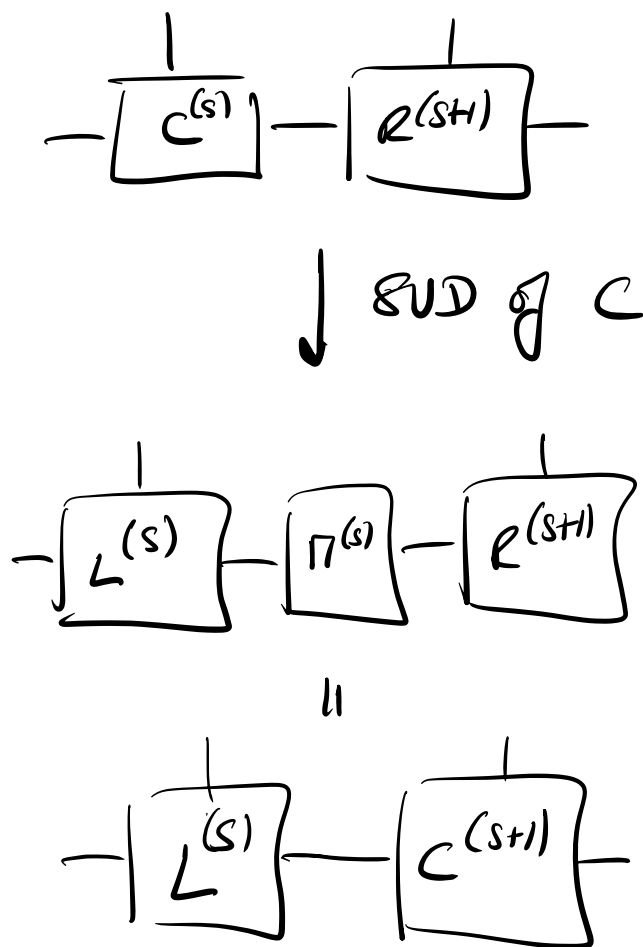
An MPS is in mixed CF,

$$\overline{L^{(1)}} - \overline{L^{(2)}} - \dots - \overline{L^{(S-1)}} - \overline{C^{(S)}} - \overline{R^{(S+1)}} - \dots - \overline{R^{(N)}}$$

where the $L^{(k)}$ are n left-CT, and
the $R^{(k)}$ are n right-CT.

s is called the "working site".

Important: The working site can be moved
to the left/right, $s \rightarrow s \pm 1$, by up-
dating only two tensors, e.g.



Now can, formal $\rightarrow$ Exercise #36.

4. Periodic, translational invariant, & infinite MPS

MPS can also be defined with periodic boundary conditions (PBC):

Periodic MPS: A PBC MPS is of the form

$$| \psi \rangle = \left[A^{(1)} - A^{(2)} - \dots - A^{(N)} \right]$$

$$= \sum_{i_1, \dots, i_N} \text{tr} \left[A^{i_1, (1)} \cdot A^{i_2, (2)} \cdot \dots \cdot A^{i_N, (N)} \right] | i_1, \dots, i_N \rangle$$

In particular, PBC MPS can be chosen to be translational invariant:

Translational invariant (tinv) PBC MPS:

A tinv. PBC MPS is obtained by choosing all tensors $A^{(k)}$ to be identical, $A^{(k)} \equiv A$:

$$|4\rangle = \boxed{A} - \boxed{A} - \dots - \boxed{A}$$

$$= \sum_{i_1, \dots, i_N} \text{tr} [A^{i_1} \cdot A^{i_2} \cdot \dots \cdot A^{i_N}] |i_1, \dots, i_N\rangle$$

We can also use this to define therm. states directly in the "thermodynamic limit" $N \rightarrow \infty$, i.e., or infinite chains.

More on this later.

Important advantage of therm. MPS:

State is described by $O(1)$ parameters,
indep. of system size N ,

and we can describe state on any
system size N with one set of parameters

5. Examples

a) Product States

Product State

$$|\psi\rangle = |\phi_1\rangle \otimes |\phi_2\rangle \otimes \dots \otimes |\phi_N\rangle.$$

$$\text{let } |\phi_s\rangle = \sum_{i_s=0}^{d-1} a^{i_s, (s)} |i_s\rangle$$

Then,

$$|\psi\rangle = \left(\sum_{i_1=0}^{d-1} a^{i_1, (1)} |i_1\rangle \right) \otimes \left(\sum_{i_2=0}^{d-1} a^{i_2, (2)} |i_2\rangle \right) \otimes \dots$$

$$= \sum_{i_1, \dots, i_N=0}^{d-1} a^{i_1, (1)} a^{i_2, (2)} \dots a^{i_N, (N)} |i_1, \dots, i_N\rangle,$$

$\Rightarrow$ MPS with $D=1$, where the matrices $A^{i_s, (s)}$ are numbers,

$$A^{i_s, (s)} = a^{i_s, (s)}.$$

$\Rightarrow$ Product states are a special case (in fact, the simplest instance) of MPS.

b) The GHZ state

$$|GHZ\rangle = \frac{1}{\sqrt{2}} (|00\dots 0\rangle + |11\dots 1\rangle) \quad (d=2)$$

PBC twv. MPS:

$$A^0 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = |0\rangle\langle 0|$$

$$A^1 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = |1\rangle\langle 1|$$

$$\text{or} \quad \alpha - \boxed{A} - \beta = \delta_{\alpha\beta}$$

$$\text{we have } A^0 A^0 = A^0$$

$$A^1 A^1 = A^1$$

$$A^0 A^1 = 0$$

$$\Rightarrow \text{tr} [A^{i_1} A^{i_2} \dots A^{i_n}] = \begin{cases} 1 & i_1 = i_2 = \dots = i_n \\ 0 & \text{else} \end{cases}$$

$$\Rightarrow |\psi\rangle = \sum_k [A^{i_1} A^{i_2} \dots A^{i_n}] |i_1, \dots, i_n\rangle$$

$$= |0 \dots 0\rangle + |1 \dots 1\rangle$$

GHZ state up to normalization.

Can normalize e.g. by setting $A^{i_1, (1)} = \frac{1}{\sqrt{2}} A^{i_1}$,
 $A^{i_k, (k)} = A^{i_k}$, But: this breaks h.w. of representation.

Note: MPS are generally not normalized
 (cf. 6.4).

Can also be written with OBC:

$$\langle + | A^{i_1} \dots A^{i_n} | + \rangle =$$

" $\frac{|0\rangle + |1\rangle}{\sqrt{2}}$

$$= \delta_{i_1 \dots i_n} \langle + | A^{i_1} | + \rangle = \frac{1}{2}.$$

$\Rightarrow$ MPS with

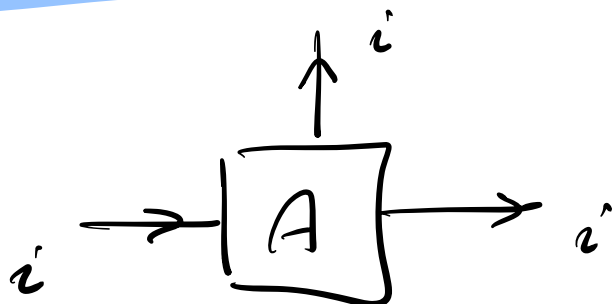
$$B^{i_1, (1)} := \sqrt{2} |+\rangle A^{i_1}$$

$$B^{i_k, (k)} := A^{i_k}$$

$$B^{i_n, (n)} := A^{i_n} |+\rangle$$

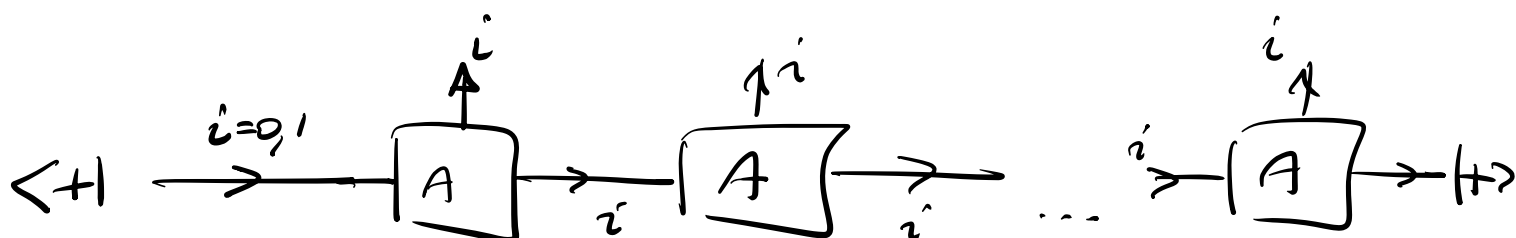
gives OBC rep. of GHZ state.

"Agent" interpretation:



A takes input i , and outputs i as a physical system, and i as a virtual system.

Total GHZ state in OBC rep.:



Each process has an amplitude associated to it;
the total amplitude is the product of the
amplitudes (cf. path integral).

Sometimes this gives a very natural perspective
on RPS.

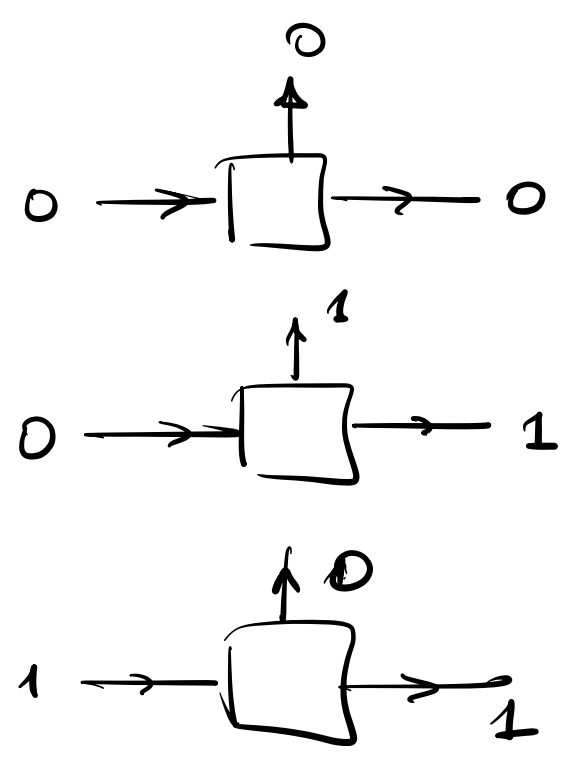
c) The W state

$$|W\rangle = \frac{1}{\sqrt{N}} (|100\dots 0\rangle + |010\dots 0\rangle + \dots + |00\dots 01\rangle)$$

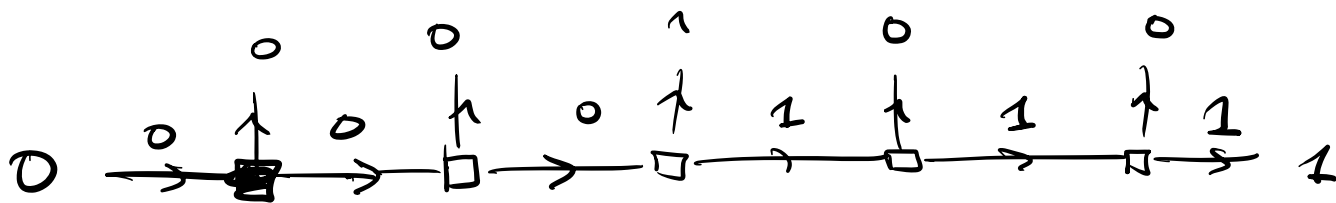
Agent picture:

① Start with 0.

② valid
transitions:



③ final configuration: 1



$$A^0 = |0 \times 0\rangle + |1 \times 1\rangle = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

$$A^1 = |0 \times 1\rangle = \sigma^-$$

$$|4\rangle = \sum_{i_1, \dots, i_N} \underbrace{\langle 0 | A^{i_1}}_{\equiv B^{i_1, (1)}} \underbrace{A^{i_2} \dots A^{i_k}}_{\equiv B^{i_k, (k)}} \underbrace{A^{i_N} | 1 \rangle}_{\equiv B^{i_N, (N)}} | i_1, \dots, i_N \rangle$$

$$\rightarrow (\sigma^-)^2 = 0, \quad \langle 0 | \sigma^- | 1 \rangle = 1.$$

$$\Rightarrow |4\rangle \propto |w\rangle$$

Note: No triv. PBC rep. of $|w\rangle$ exists, unless D grows with N .

(Any triv. OBC MPS can be transformed to a triv. PBC MPS with $D_{\text{PBC}} = N D_{\text{OBC}}$.)

2) The cluster state

The cluster state is obtained by acting with

$$CZ_{i,i+1} = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 & \\ & & & -1 \end{pmatrix} \text{ on } |+\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}},$$

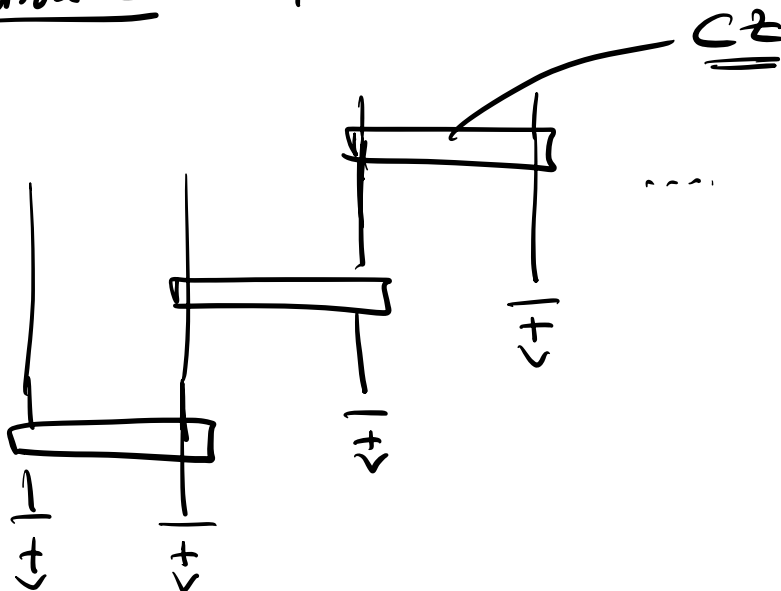
$$|\mathcal{C}\rangle = \prod_{i=1}^{N-1} CZ_{i,i+1} |+\rangle^{\otimes N} \text{ (w/OBC)}.$$

(Note: All $CZ_{i,i+1}$ commute - any order ok.)

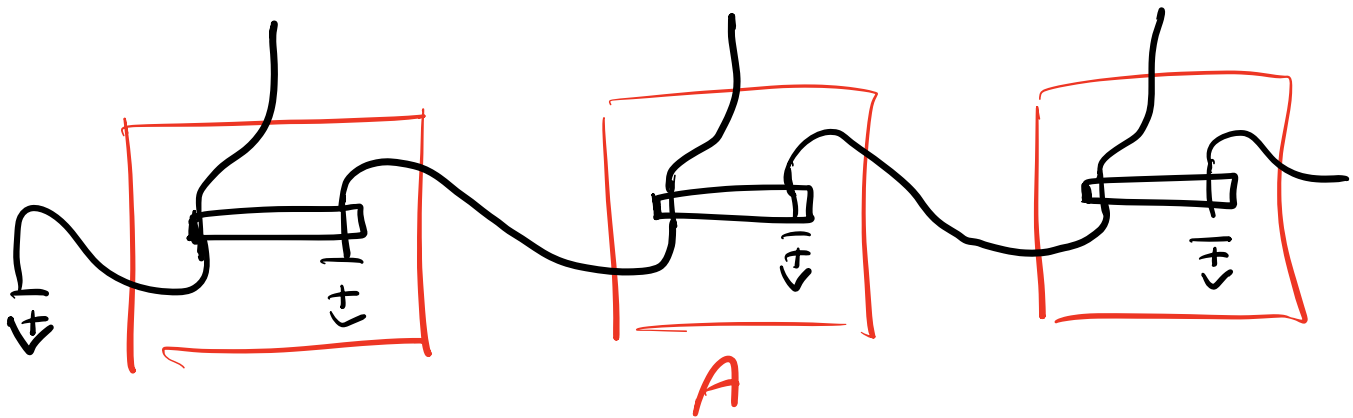
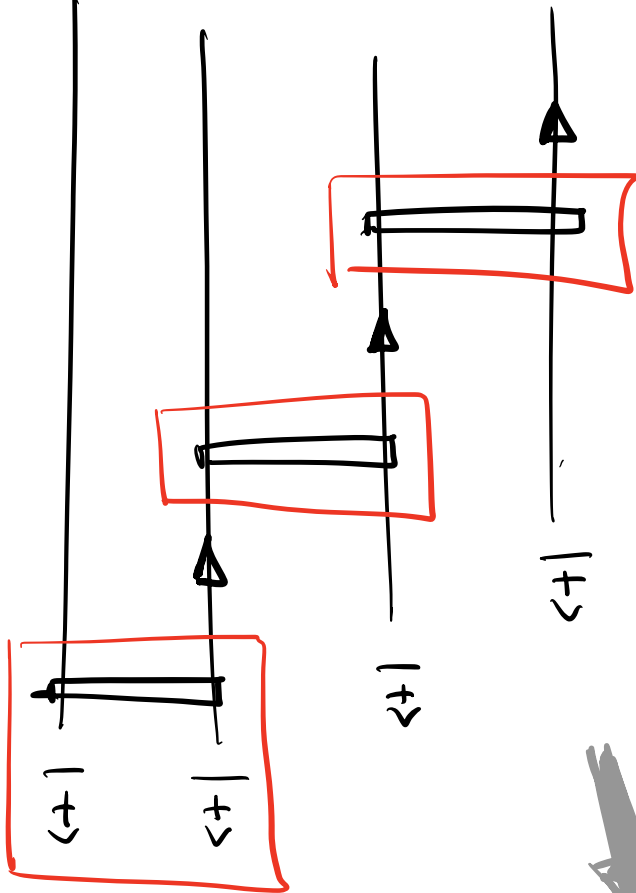
How can we find MPS representation?

Different approaches possible...

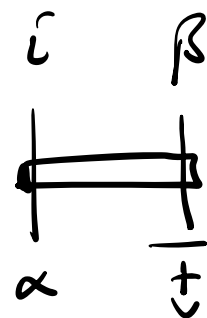
Option 1: $|\mathcal{C}\rangle =$



Agent picture:



$$\alpha - \boxed{A} - \beta =$$



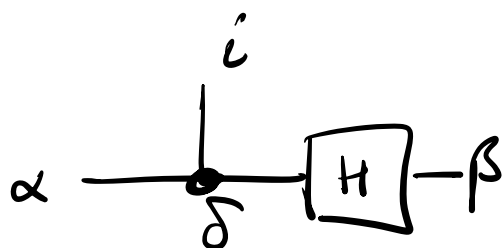
$$= \langle i | \otimes \langle \beta | C_Z \underbrace{|\alpha\rangle \otimes |+\rangle}_{\frac{|\alpha 0\rangle + |\alpha 1\rangle}{\sqrt{2}}}$$

$$\begin{array}{cc} \swarrow \alpha=0 & \searrow \alpha=1 \\ \frac{|\alpha 0\rangle + |\alpha 1\rangle}{\sqrt{2}} & \frac{|\alpha 0\rangle - |\alpha 1\rangle}{\sqrt{2}} \end{array}$$

$$\Rightarrow \langle i, \beta | \dots \rangle$$

$$\begin{array}{cc} \frac{\delta_{\alpha i}}{\sqrt{2}} \cdot (+1)^\beta & \frac{\delta_{\alpha i}}{\sqrt{2}} (-1)^\beta \\ \text{for } \alpha=0 & \text{for } \alpha=1 \end{array}$$

$$= \boxed{A}^{i\beta}$$

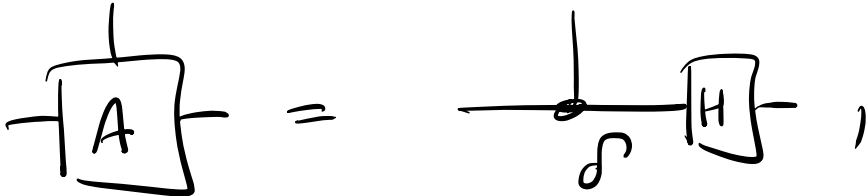


with  the δ -tensor:

$$\delta_{\alpha i \gamma} = \begin{cases} 1 & \alpha = i = \gamma \\ 0 & \text{otherwise} \end{cases}$$

and $H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = |0\rangle\langle+| + |1\rangle\langle-|$

the Hadamard matrix / transformer.

i.e.: 

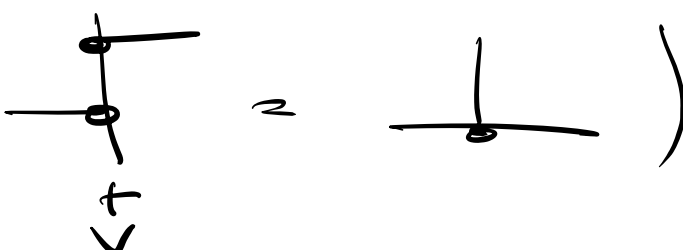
or $A^0 = |0\rangle\langle 0| \cdot H = |0\rangle\langle+|$

$A^1 = |1\rangle\langle 1| \cdot H = |1\rangle\langle-|.$

$|ee\rangle = \sum_{i_1, \dots, i_n} \langle+| A^{i_1} \dots A^{i_n} |0\rangle |i_1, \dots, i_n\rangle$

and

A diagrammatic equation. On the left, a central vertex is connected to four lines: a horizontal line to the left labeled e , a horizontal line to the right labeled j , a vertical line upwards labeled m , and a vertical line downwards labeled i . The top-left and bottom-left corners of the vertex are marked with δ . Below this diagram is a box containing a plus sign and a checkmark. This is followed by an equals sign and a second diagram. The second diagram is identical to the first, but the top-left corner is marked with δ and the bottom-left corner is marked with σ . To the right of the second diagram is an exclamation mark.

(and same for )

$\Rightarrow$ same MPS representation
(but this also works for PBC).

6. Properties of MPS: Norms, expectation values, correlations.

How can we evaluate properties of MPS:

- * normalization
- * expectation values, energies
- * correlation functions

...

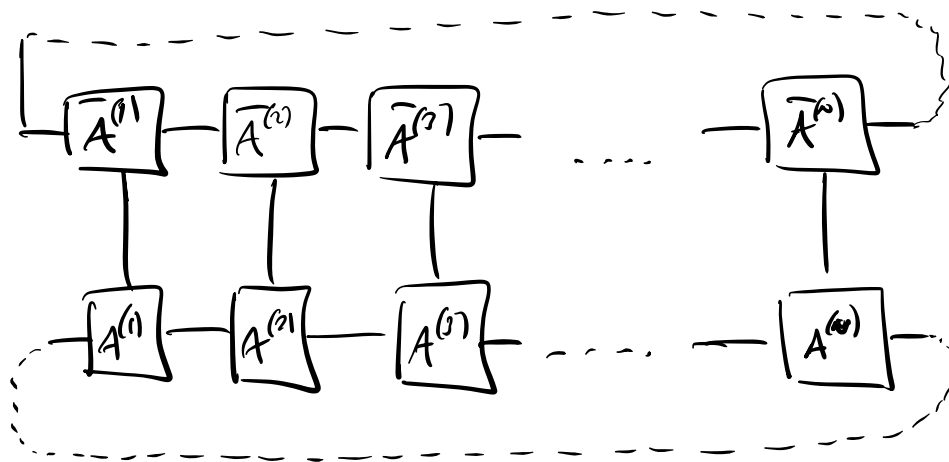
What do they depend on?

Can this be done efficiently - that is, without having to compute c_{ij}, i, j , but rather in true $\text{poly}(D)$?

a) Normalization

Consider 1D PBC MPS (OBC is special case with $D_0 = D_N = 1$).

$$\langle \psi | \psi \rangle =$$



Define

$$\mathbb{E}^{(k)} = \begin{array}{c} \alpha' \quad \beta' \\ \boxed{\mathbb{E}^{(k)}} \\ \alpha \quad \beta \end{array} = \begin{array}{c} \alpha' \quad \beta' \\ \boxed{\bar{A}^{(k)}} \\ \downarrow i \\ \boxed{A^{(k)}} \\ \alpha \quad \beta \end{array}$$

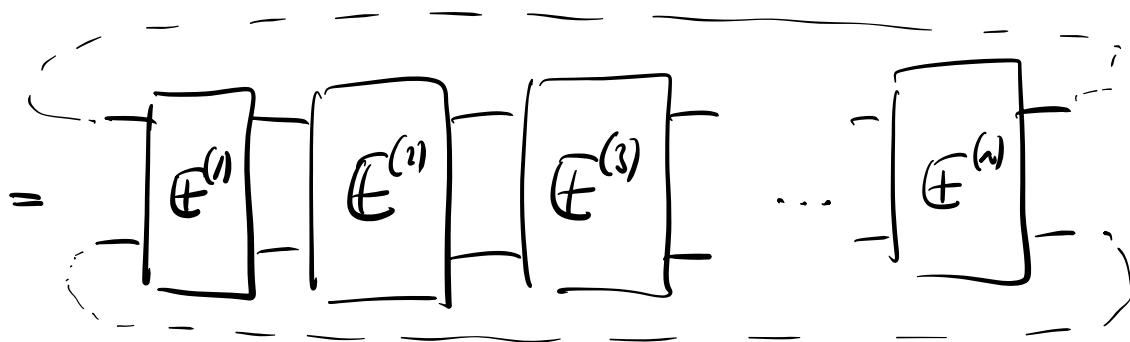
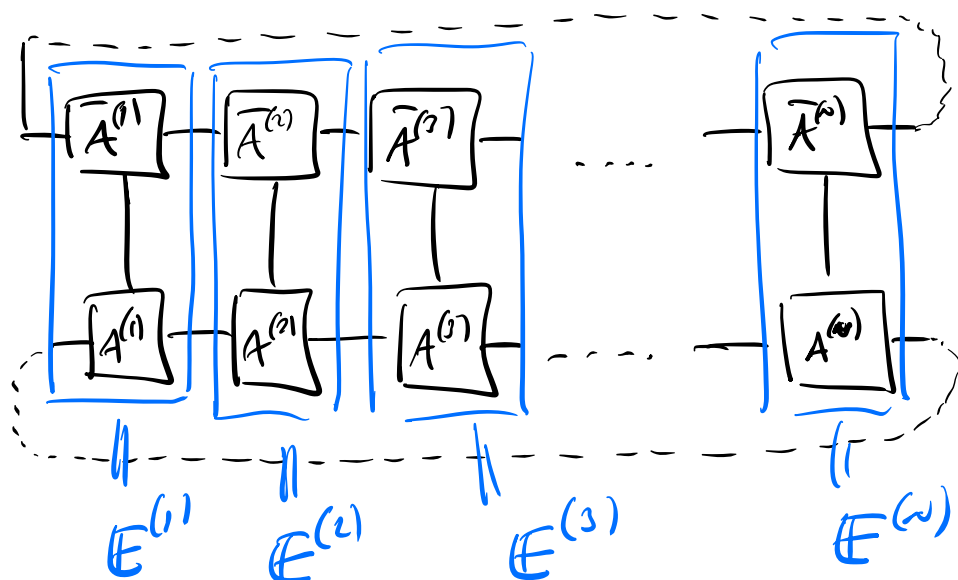
$$= \sum A^{i,(k)} \otimes \bar{A}^{i,(k)}$$

— interpreted as a $D^2 \times D^2$ matrix with row index (α, α') , col. index (β, β') .

$\mathbb{E}$ is also called the transfer matrix or transfer operator.

Then,

$$\langle \psi | \psi \rangle =$$



$$= \text{tr} \left(E^{(1)} \cdot E^{(2)} \cdot E^{(3)} \cdot \dots \cdot E^{(n)} \right)$$

For OBC, $E^{(1)}$ & $E^{(n)}$ are vectors.

What is the comp. cost (for simplicity, $D_k \equiv D \ \forall k$)?

PBC: Need to multiply two $D^2 \times D^2$

matrices in each step.

Comp. cost of a matrix product of a

$(a \times b) \times (b \times c)$ matrix:

$a \cdot b \cdot c$ operations.

$\Rightarrow$ Computational cost is D^6 per step,
i.e. ND^6 in total (vs. d^N for building
 $c_1, \dots, c_N$).

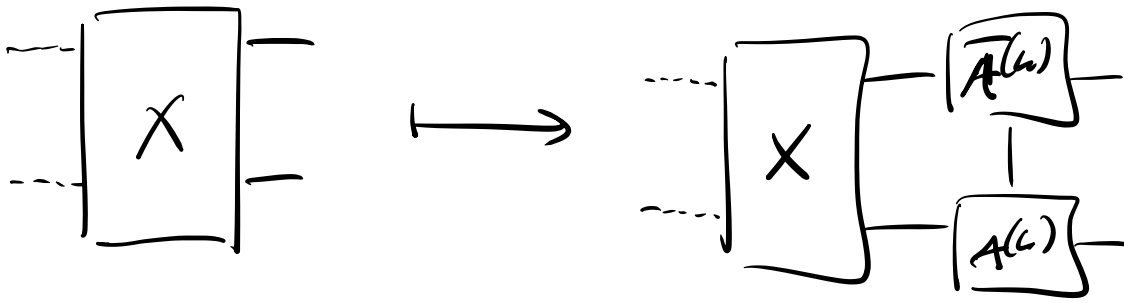
OBC: If we start from the right:

$$\underbrace{\underbrace{E^{(N-1)}}_{D^2 \times D^2} \underbrace{E^{(N)}}_{D^2 \times 1}}_{D^2 \times 1 \text{ -vector}} \Rightarrow D^4 \text{ operations.}$$

$\Rightarrow$ normalizations can be computed efficiently.

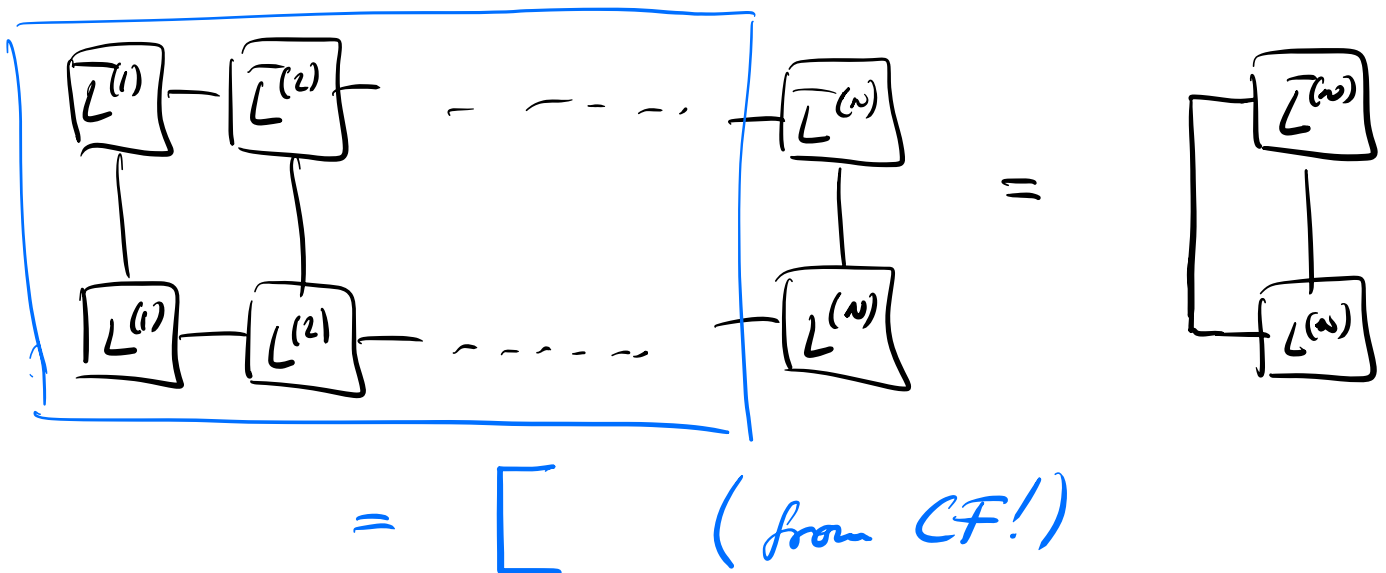
Important points for numerical simulations:

* The PBC/OBC scaling can be improved to D^5/D^3 by applying

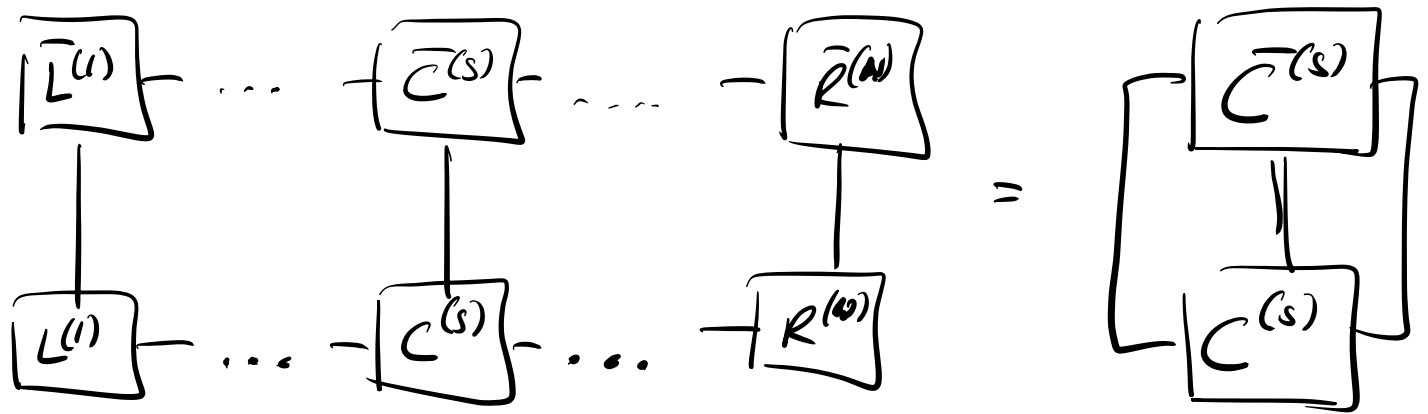


without building $E^{(L)}$.

* By using the left - (or right -) canonical form, the computation can be done in $O(1)$ steps:



* Similarly, for a mixed CF:

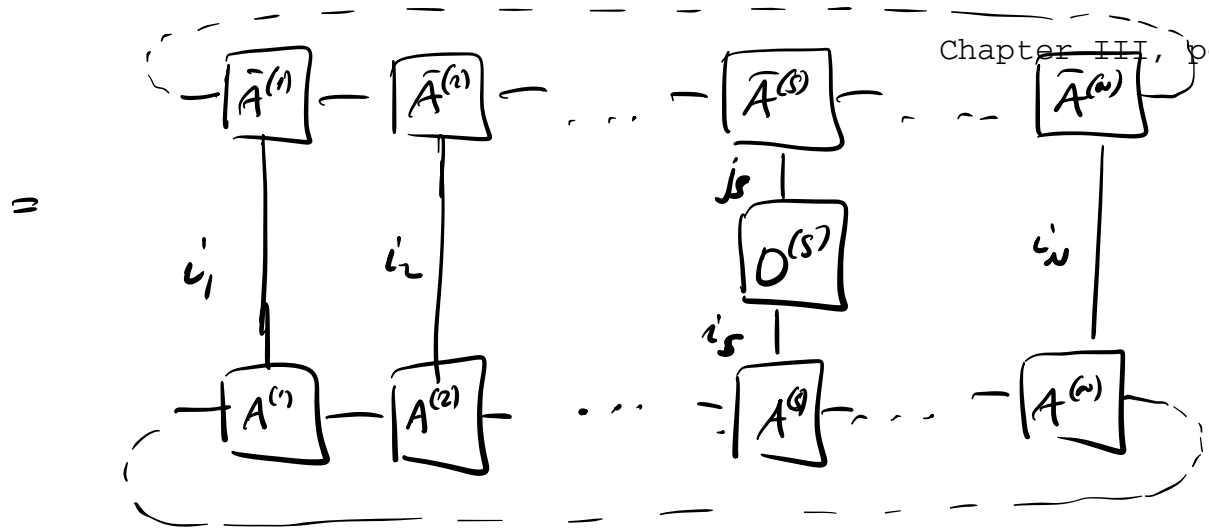


$$= \|C^{(s)}\|_2^2 = \sum_{i_r, j_s} |C_{\alpha\beta}^{i_r(s)}|^2$$

6) Expectation values

Expectation values $\langle \psi | O | \psi \rangle$ of local observables, e.g. single-site observables $O^{(s)}$ such as $O^{(1)} = \sigma_z^{(1)}$:

$$\begin{aligned} \langle \psi | O^{(1)} | \psi \rangle &= \sum \bar{c}_{j_1 \dots j_N} c_{i_1 \dots i_N} \langle j_1 \dots j_N | \sigma^{(1)} | i_1 \dots i_N \rangle \\ &= \sum_{\substack{i_1 \dots i_N \\ j_s}} \bar{c}_{i_1 \dots i_{s-1} j_s i_{s+1} \dots i_N} c_{i_1 \dots i_N} \underbrace{O_{j_s i_s}^{(s)}}_{= \langle j_s | O^{(s)} | i_s \rangle} \end{aligned}$$



... can also be understood by noting that

$$O^{(s)} = \mathbb{1} \otimes O^{(s)} \otimes \mathbb{1} = \begin{pmatrix} | & | & \dots & | & \boxed{O^{(s)}} & | & \dots & | \end{pmatrix}.$$

Can it be computed efficiently?

Define again $E^{(s)}$ as before, and additionally

$$E_O^{(s)} = \begin{pmatrix} \boxed{\bar{A}^{(s)}} \\ | \\ \boxed{O} \\ | \\ \boxed{A^{(s)}} \end{pmatrix} = \sum_{i,j} A^{i(s)} \otimes \bar{A}^{j(s)} \langle j|O|i \rangle$$

(Note that $E_{\mathbb{1}}^{(s)} \equiv E^{(s)}$.)

Then, we have that

$$\langle \psi | O | \psi \rangle = \text{tr} \left[E^{(1)} \dots E^{(s-1)} E_O^{(s)} E^{(s+1)} \dots E^{(N)} \right]$$

(PBC)

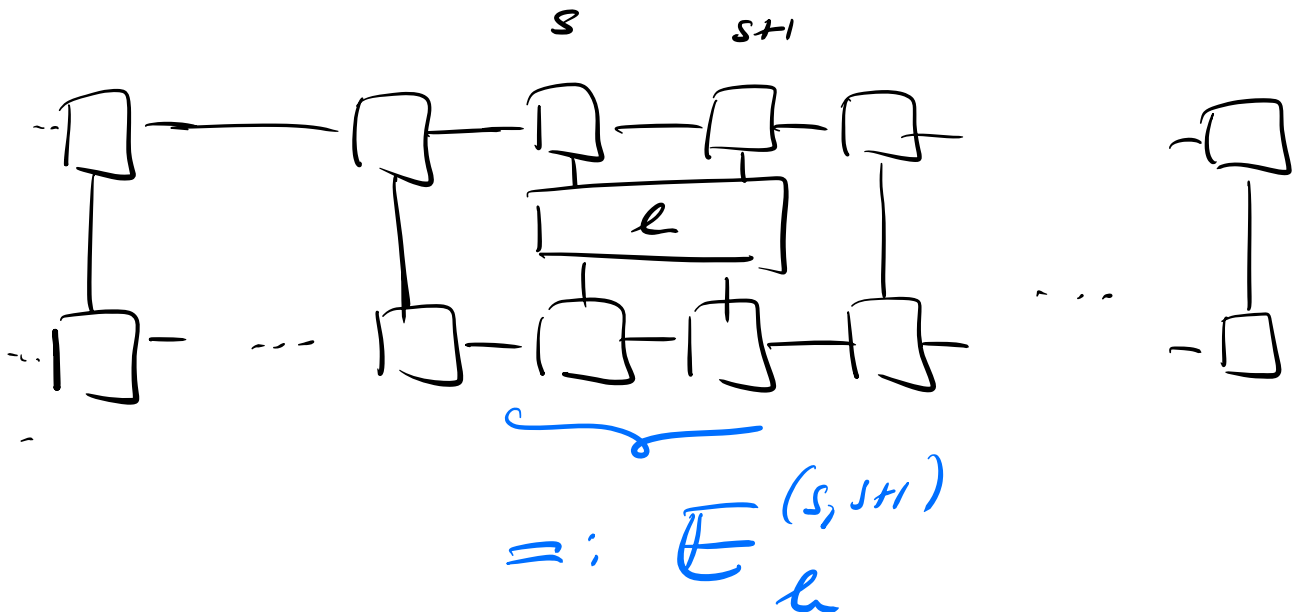
or for OBC,

$$\langle \psi | O | \psi \rangle = E^{(1)} \dots E^{(s-1)} E_O^{(s)} E^{(s+1)} \dots E^{(N)}$$

$\Rightarrow$ expectation values can be computed efficiently.

Same for 2-site observables, e.g. 2-body

Hamiltonians:



* define transfer operator for block on which h acts, then

$$\langle \psi | h | \psi \rangle = E^{(1)} \dots E^{(s-1)} E^{(s,s+1)} E^{(s+2)} \dots$$

* or decompose $h = \sum_i a_i \otimes b_i$, and

use

$$\langle \psi | h | \psi \rangle = \sum_{i,j} E^{(1)} \dots E^{(s-1)} E^{(s)}_{a_i} E^{(s+1)}_{b_i} \dots$$

Possible optimizations (e.g. for numerics):

* We can again use a gauge condition - ideally mixed gauge around h - to reduce the computational cost to $O(1)$.

* For $\langle \psi | H | \psi \rangle = \sum_s \langle \psi | h_s | \psi \rangle$, there is no single "good" gauge, but we can still re-use results, e.g.:

$$\langle \psi | h_{s+1,s} | \psi \rangle = \boxed{E^{(1)} E^{(2)} \dots E^{(s-2)}} E^{(s-1,s)} E^{(s+1)} \boxed{E^{(s+2)} \dots}$$
$$\langle \psi | h_{s,s+1} | \psi \rangle = \boxed{E^{(1)} E^{(2)} \dots E^{(s-2)}} E^{(s+1)} E^{(s,s+1)} \boxed{E^{(s+2)} \dots}$$

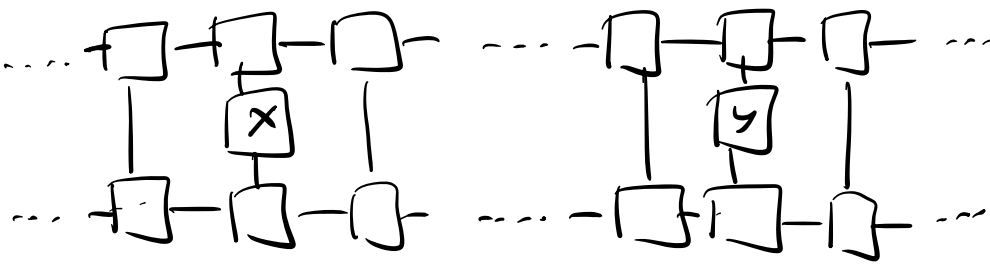


$\Rightarrow$ total effort to compute $\langle \psi | H | \psi \rangle = \sum_s \langle \psi | h_s | \psi \rangle$
scales proportional with $N!$

c) Correlation functions

What about correlation functions between operators X_i, Y_j at sites i & j ?

$\langle \psi | X_i Y_j | \psi \rangle =$



$$= E^{(1)} \dots E^{(i-1)} E_x^{(i)} E^{(i+1)} \dots E^{(j-1)} E_y^{(j)} E^{(j+1)} \dots$$

$\Rightarrow$ again efficient.

d) State vs. transfer operator

Properties of state apparently determined mostly by $\{\mathbb{E}^{(k)}\}$, together with $\mathbb{E}_0^{(k)}$.

How much information about the state does $\{\mathbb{E}^{(k)}\}$ encode?

Theorem: A given transfer matrix $\mathbb{E} \equiv \mathbb{E}^{(k)}$

fixes the tensor $A \equiv A^{(k)}$ up to a local basis transformation on the physical system, i.e., for any pair $A^i, \bar{A}^i$ s.t.

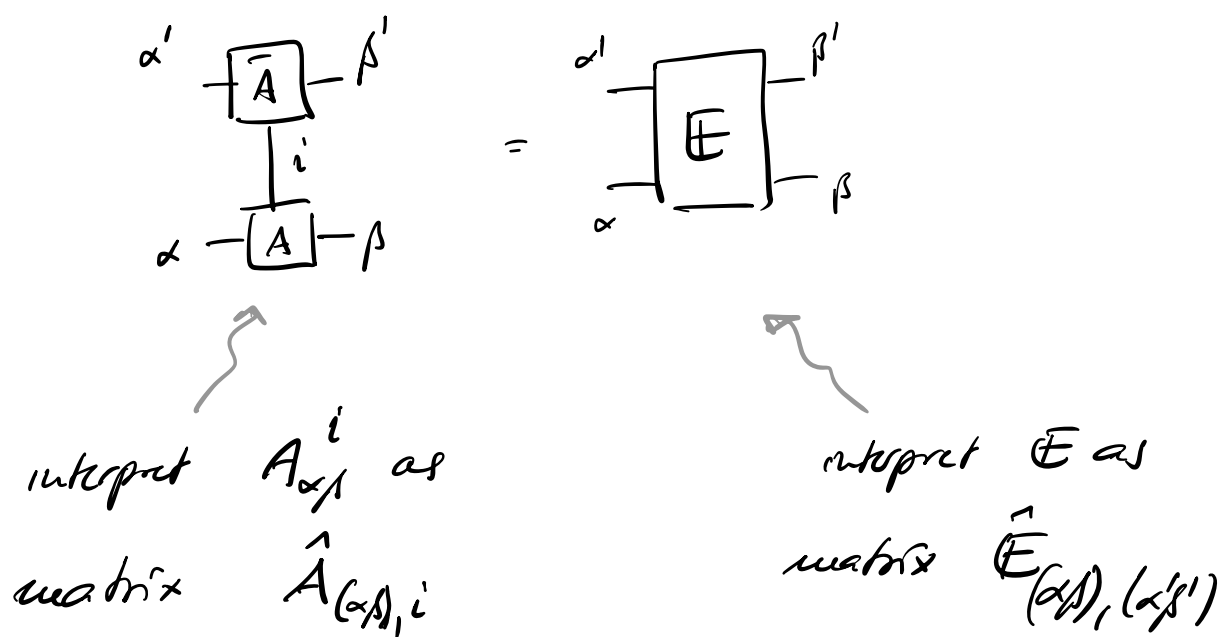
$$\mathbb{E} = \sum A^i \otimes \bar{A}^i = \sum B^i \otimes \bar{B}^i,$$

$$\exists U_{ij} \text{ unitary} : A^i = \sum_j U_{ij} B^j$$

In fact, this even holds when the physical dimensions are different, with U a (partial)

$\Rightarrow$ all non-local properties of an NPS are encoded in the $\{\mathbb{E}^{(i)}\}$.

Proof sketch:



$$\hat{\mathbb{E}} = \hat{A} \cdot \hat{A}^{\dagger}.$$

What is relation betw. $\hat{A}, \hat{B}$ with $\hat{A}\hat{A}^{\dagger} = \hat{B}\hat{B}^{\dagger}$?

$\hat{\mathbb{E}} \geq 0$, and thus $\hat{\mathbb{E}} = U D^2 U^{\dagger}$, with

U isometry, $D = \begin{pmatrix} s_1 & & \\ & \ddots & \\ & & s_r \end{pmatrix}$, $s_1 \geq \dots \geq s_r > 0$

(as in construction of SVD). Then,

$$\hat{A} \hat{A}^\dagger = \hat{B} \hat{B}^\dagger = \hat{E} \Rightarrow \text{SVDs of } \hat{A} \text{ and } \hat{B} \text{ are}$$

$$\hat{A} = U D V_A^\dagger$$

$$\hat{B} = U D V_B^\dagger, \quad V_A, V_B \text{ are unitaries}$$

(From a quantum information perspective, this is equivalent to the ambiguity of purification, as $\square$)

$\sum_i A_{\alpha\beta}^i |\alpha, \beta\rangle \otimes |i\rangle$ is a purification of

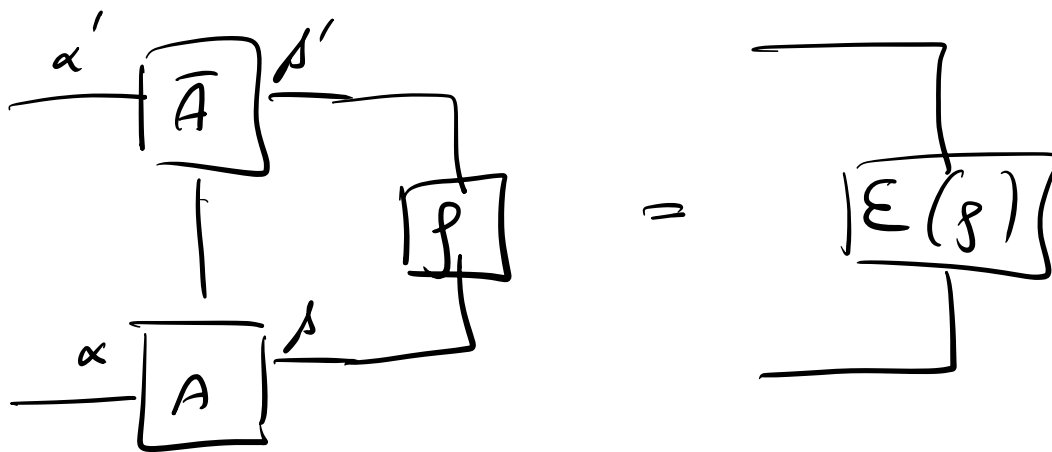
$$\rho = \sum_{(\alpha\alpha'), (\beta\beta')} E_{(\alpha\alpha'), (\beta\beta')} |\alpha\beta\rangle \langle \alpha'\beta'|$$

e) Transfer operator as a CP map

One more connection to quantum information:

The transfer operator E defines a

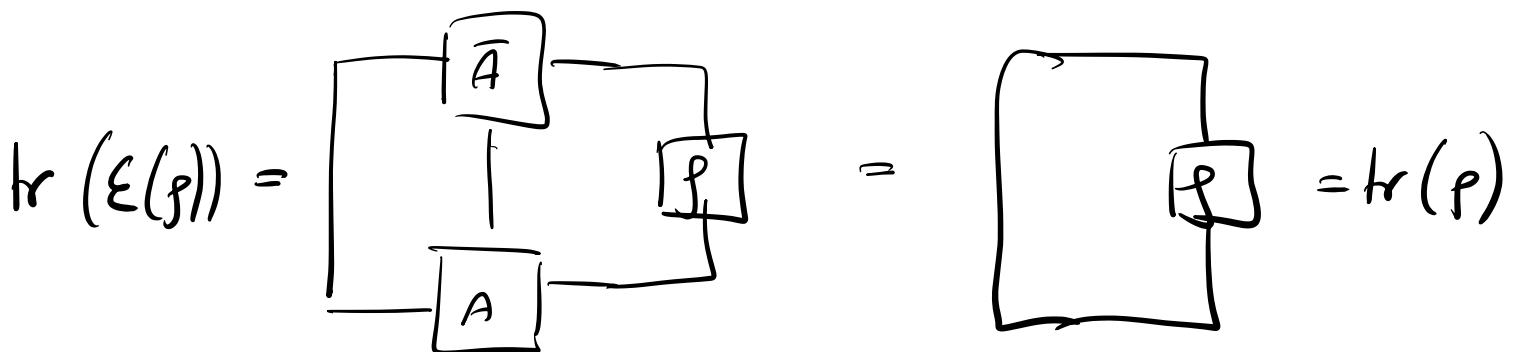
map $\rho \mapsto E(\rho)$ by virtue of



We have
$$\begin{aligned} E(p) &= \sum A_{\alpha\beta}^i \bar{A}_{\alpha'\beta'}^i p_{\beta\beta'} / \alpha \chi \alpha' \\ &= \sum A^i \cdot p \cdot (A^i)^\dagger \end{aligned}$$

$\Rightarrow E(\cdot)$ is a completely positive map.

(If the MPS is in left-canonical form,
then $E(\cdot)$ is also trace-preserving:



7. Translational invariant infinite MPS:

Construction and correlations

Knowing the transfer operator, we can now
construct trans. MPS in the thermodyn. limit.

a) Construction

Consider a trans. PBC MPS with tensor A ,

$$E = \sum A^i \otimes \bar{A}^i, \text{ on a chain of length } N.$$

The expectation value of an operator O
at position 1 (Note: trans. $\Rightarrow$ all positions
equiv.!) is

$$\langle \psi | O | \psi \rangle = \text{tr} \left[E_0 \cdot \underbrace{E \cdots E}_{N-1 \text{ times}} \right]$$

trans: all E the same!

$$= \text{tr} [E_0 E^{N-1}].$$

and the normalization

$$\langle \psi | \psi \rangle = \text{tr} [E^N].$$

Assume E diagonalizable (generic!):

$$E = \sum \lambda_i |r_i\rangle \langle l_i|$$

eigenvalue decomposition.

(Note: $\langle l_i | r_j \rangle = \delta_{ij}$, but

$\langle l_i | r_j \rangle, \langle r_i | r_j \rangle$ arbitrary!)

Wlog: $|\lambda_1| \geq |\lambda_2| \geq \dots$

Then, $E^L = \sum \lambda_i^L |r_i\rangle \langle l_i|$.

Assume $|\lambda_1| > |\lambda_2| \geq \dots$

largest eigenval non-degen.
(in absolute value)

Then, as $l \gg 1$,

$$E^l \rightarrow \lambda_1^l / r_1 \chi_{l_1}.$$

(*)

→ Note: This even holds for non-diagonalizable E , since for CP maps, the largest eigenvalue cannot have a Jordan block.
i.e.: The following argument always applies, given that λ_1 is non-degenerate.

Thus, as $N \rightarrow \infty$:

$$\frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\text{tr} [E_0 E^{N-1}]}{\text{tr} [E^N]}$$

$$= \frac{\sum_i \text{tr} [E_0 \lambda_i^{N-1} / r_i \chi_{l_i}]}{\sum_i \text{tr} [\lambda_i^N / r_i \chi_{l_i}]}$$

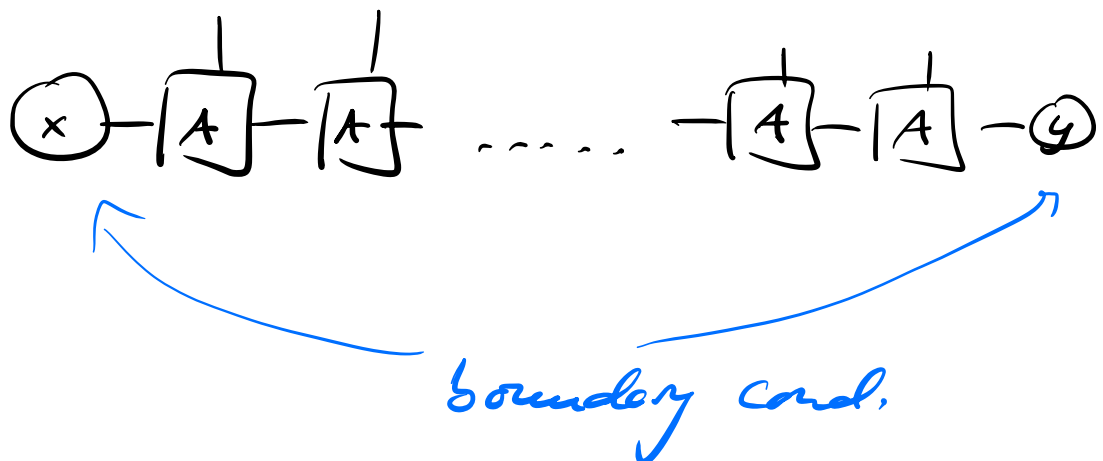
$$= \frac{\sum_i \lambda_i^{N-1} \langle l_i | E_0 | r_i \rangle}{\sum_i \lambda_i^N \underbrace{\langle l_i | r_i \rangle}_{=1}}$$

$$\rightarrow \frac{\lambda_1^{N-1} \langle l_1 | E_0 | r_1 \rangle}{\lambda_1^N}$$

$$= \frac{1}{\lambda_1} \langle l_1 | E_0 | r_1 \rangle.$$

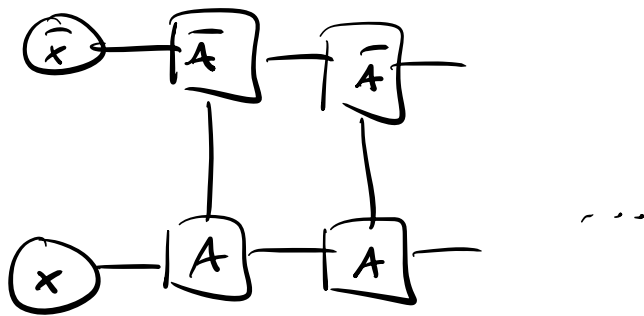
We find:

- $\frac{\langle \psi | O | \psi \rangle}{\langle \psi | \psi \rangle}$ is well-defined in the thermodynamic limit.
- This can be used to compute exp. values for any quantity, by choosing left/right boundaries $\langle l_n |$ and $| r_n \rangle$ (example - correlations - in a moment!)
- The same result can be obtained from OBC:



let $X = x \otimes \bar{x}$, $Y = y \otimes \bar{y}$ the two-layers

boundary condition:



$$\frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\langle x | E^\pi E_0 E^\pi | y \rangle}{\langle x | E^{2\pi H} | y \rangle}.$$

Using $E = \sum \lambda_i / r_i |e_i\rangle \rightarrow \lambda_i / r_i |e_i\rangle$,

for $\pi \rightarrow \infty$ we have

$$\frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} \rightarrow \frac{\lambda_1^{2\pi} \langle x | r_1 \rangle \langle e_1 | y \rangle \langle e_1 | E_0 | r_1 \rangle}{\lambda_1^{2\pi+1} \langle x | r_1 \rangle \langle e_1 | y \rangle}$$

$$= \frac{1}{\lambda_1} \langle e_1 | E_0 | r_1 \rangle.$$

b) Correlation functions

How do correlations in a therm. (infinite) RPS look like?

$$\frac{\langle \psi | X_1 Y_\ell | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\text{tr} [E_x E^{\ell-2} E_y E^{N-\ell}]}{\text{tr} [E^N]}$$

$$\xrightarrow{N \rightarrow \infty} \frac{\lambda_1^{N-\ell} \langle \ell_1 | E_x E^{\ell-2} E_y | \ell_1 \rangle}{\lambda_1^N}$$

$$= \frac{1}{\lambda_1^\ell} \langle \ell_1 | E_x \left(\sum_i \lambda_i | \ell_i \rangle \langle \ell_i | \right)^{\ell-2} E_y | \ell_1 \rangle$$

assume diagonalizable

$$= \sum_i \left(\frac{\lambda_i}{\lambda_1} \right)^{\ell-2} \frac{\langle \ell_1 | E_x | \ell_i \rangle}{\lambda_1} \frac{\langle \ell_i | E_y | \ell_1 \rangle}{\lambda_1}$$

If both $|\lambda_1|$ and $|\lambda_2|$ are non-degenerate,
then for $\ell \gg 1$:

$$\approx \underbrace{\frac{\langle e_1 | E_x | e_1 \rangle}{\lambda_1}}_{= \langle \psi | X | \psi \rangle} \underbrace{\frac{\langle e_1 | E_y | e_1 \rangle}{\lambda_1}}_{= \langle \psi | Y | \psi \rangle} +$$

$$\underbrace{\frac{\langle e_1 | E_x | e_2 \rangle \langle e_2 | E_y | e_1 \rangle}{\lambda_1 \lambda_1}}_{=: C} \left(\frac{\lambda_2}{\lambda_1} \right)^{e-2}$$

$$= \langle \psi | X | \psi \rangle \langle \psi | Y | \psi \rangle + C \cdot \left(\frac{\lambda_2}{\lambda_1} \right)^{-2} \cdot e^{-e/\xi},$$

$$\text{where } \xi = - \frac{1}{\log(\lambda_2/\lambda_1)}.$$

Observation: In a translational invariant

MPS with transfer matrix spectrum

$\{\lambda_1, \lambda_2, \dots\}$, if $|\lambda_1|$ is non-degenerate,

correlation functions decay exponentially,

with correlation length $\xi = -1/\log |\lambda_2/\lambda_1|$.

In particular, the connected correlation function

$$\langle (x_i - \langle x_i \rangle) (y_e - \langle y_e \rangle) \rangle$$

$$= \langle x_i y_e \rangle - \langle x_i \rangle \langle y_e \rangle$$

(where $\langle \cdot \rangle = \langle \psi | \cdot | \psi \rangle$) decays exponentially to zero.

Note: We can avoid the normalization & rescaling by λ_1 by replacing

$$A \longrightarrow \frac{1}{\sqrt{\lambda_1}} A ; \text{ the new } \mathbb{E} \text{ has } \lambda_1 = 1.$$

c) Long-range order in two NPS

Conversely, if $|\lambda_1|$ is degenerate, i.e.

$$|\lambda_1| = |\lambda_2| > |\lambda_3| \geq \dots, \text{ then}$$

$$\frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\sum \lambda_i^{N-1} \langle r_i | E_0 | r_i \rangle}{\sum \lambda_i^N}$$

$$\xrightarrow{N \rightarrow \infty} \frac{\lambda_1^{N-1} \langle r_1 | E_0 | r_1 \rangle + \lambda_2^{N-1} \langle r_2 | E_0 | r_2 \rangle}{\lambda_1^N + \lambda_2^N}$$

If we assume $\lambda_1 = \lambda_2$, then this means

$$\frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{1}{2} \left(\frac{\langle r_1 | E_0 | r_1 \rangle}{\lambda_1} + \frac{\langle r_2 | E_0 | r_2 \rangle}{\lambda_2} \right),$$

— this looks like an average of two states.

In fact, with OBC, we have

$$\begin{aligned} \frac{\langle \psi | 0 | \psi \rangle}{\langle \psi | \psi \rangle} &= \frac{\sum_{i=1,2} \langle x | r_i \rangle \langle r_i | y \rangle \langle r_i | E_0 | r_i \rangle}{\sum_{i=1,2} \langle x | r_i \rangle \langle r_i | y \rangle \lambda_i} \\ &= \frac{\langle e(x) | E_0 | r(y) \rangle}{\langle e(x) | r(y) \rangle \lambda_1} \end{aligned}$$

with $|r(y)\rangle = \sum_{i=1,2} |r_i\rangle \langle l_i| y\rangle,$

$$\langle l(x)| = \langle x| \sum_{i=1,2} |r_i\rangle \langle l_i|$$

i.e. by choosing the boundary conditions x and y we can change the expectation value in the middle: The system is sensitive to boundary conditions!

Now consider the correlation function for some given boundary condition:

$$\frac{\langle \psi | X_1 Y_\ell | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\langle l(x) | E_x E^{\ell-2} E_y | r(y) \rangle}{\lambda_1^\ell \langle l(x) | r(y) \rangle}$$

$$= \frac{\langle l(x) | E_x \left(\sum_i \lambda_i^{\ell-2} |r_i\rangle \langle l_i| \right) E_y | r(y) \rangle}{\lambda_1^\ell \langle l(x) | r(y) \rangle}$$

$$l \gg 1 \rightarrow \frac{\langle e(x) | \mathbb{E}_x (\lambda_1^{l-2} |r_1 \chi_{e_1}| + \lambda_2^{l-2} |r_2 \chi_{e_2}|) \mathbb{E}_y |r(y)\rangle}{\lambda_1^l \langle e(x) | r(y) \rangle}$$

(for $\lambda_1 = \lambda_2$)

$$\lambda_1^l \langle e(x) | r(y) \rangle$$

$$= \frac{\langle e(x) | \mathbb{E}_x |r_1\rangle \langle r_1 | \mathbb{E}_y |r(y)\rangle + \langle e(x) | \mathbb{E}_x |r_2 \chi_{e_2}| \mathbb{E}_y |r(y)\rangle}{\lambda_1^2 \langle e(x) | r(y) \rangle}$$

This is generally non-zero even for the connected correlation functions:

$$\langle (x - \langle x \rangle)(y - \langle y \rangle) \rangle$$

$$= \langle xy \rangle - \langle x \rangle \langle y \rangle$$

//

//

$$\frac{\langle e(x) | \mathbb{E}_x (\sum_{i=1,2} |r_i \chi_{e_i}|) \mathbb{E}_y |r(y)\rangle}{\lambda_1^2 \langle e(x) | r(y) \rangle}$$

$$\lambda_1^2 \langle e(x) | r(y) \rangle$$

//
Ⓐ

$$\neq \frac{\langle e(x) | \mathbb{E}_x |r(y)\rangle}{\lambda_1 \langle e(x) | r(y) \rangle} \times$$

//
Ⓑ

$$\frac{\langle e(x) | \mathbb{E}_y |r(y)\rangle}{\lambda_1 \langle e(x) | r(y) \rangle}$$

$$// \lambda_1 \langle e(x) | r(y) \rangle$$

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Example: GHZ state, $A^0 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $A^1 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$.

$$E = A^0 \otimes \bar{A}^0 + A^1 \otimes \bar{A}^1 = \begin{pmatrix} 1 & & & \\ & 0 & & \\ & & 0 & \\ & & & 1 \end{pmatrix}.$$

$$\lambda_1 = \lambda_2 = 1, \quad \lambda_3 = \lambda_4 = 0.$$

leading eigenvectors: $|r_1\rangle = |e_1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix},$
 $|r_2\rangle = |e_2\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}.$

Let $X = Y = \sigma_z$:

$$E_x = E_y = E_{\sigma_z} = \begin{pmatrix} 1 & & & \\ & 0 & & \\ & & 0 & \\ & & & -1 \end{pmatrix}$$

Choose $|e(x)\rangle = |r(x)\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix},$

Then, $\textcircled{A} = 1,$

$$\textcircled{B} = \textcircled{C} = 0.$$

Observation:

NPS with a degenerate leading eigenvalue
have long-range correlations

$$\langle X_i, Y_e \rangle \rightarrow \text{const} \neq 0$$

for suitable X_i, Y_e .

Observation:

NPS always have either
 * exponentially decaying correlations or
 * long range correlations.

Translational invariant NPS with finite D
cannot exactly reproduce states with
algebraically decaying correlations

$$\langle X_i, Y_e \rangle \sim \frac{1}{\ell^\alpha},$$

and thus cannot exactly reproduce

But: Correlation functions in MPS are the sum of D^2 exponentials, which can be used to approximate algebraic correlators within a certain range.

Note: There are also constraints to the ability of MPS to exactly capture ground states of gapped systems:

- gapped states cannot be exactly written as MPS, since the Schmidt rank for gapped systems in the ground state is maximal.
- Moreover, also gapped systems typ. don't have corr. w/ exact exponential decay,

but rather of Ornstein-Zernike form

$$\langle x_i y_j \rangle \sim \frac{1}{\sqrt{\ell}} e^{-\ell/\xi}, \quad \ell = |i-j|.$$

$\Rightarrow$ must also be approx. by exponentials.